

OPERATING INSTRUCTIONS

DINO

160XT II

180XT II

210XT II



Manufacturer:

DINOLift
UP TO THE JOB

Raikkolantie 145

FI-32210 LOIMAA

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Dealer:



TRANSLATION OF ORIGINAL OPERATING INSTRUCTIONS

Valid from serial number:

160XT II	17156 ->
180XT II	20001, 30002 ->
210XT II	3370 ->

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1. TO THE OPERATOR

Keep this manual on the work platform of the lift in the box reserved for it. If the instruction manual gets lost, damaged, or for some other reason becomes unreadable, order a new manual from the manufacturer.

This manual is intended to familiarise the user with the structure and functions of the work platform, as well as with its appropriate use. The manual provides guidance on the service measures that are the responsibility of the user of the work platform.

Other maintenance procedures on the work platform require special skills, special tools or accurate knowledge about measurements or adjusted values. Guidance for these measures is provided in a separate service manual. For situations that require service or repair measures, contact the authorised service provider, importer or manufacturer.



DANGER

Read all the instructions in this manual before using the aerial work platform. Make sure that you have understood all the instructions. The instructions must absolutely be followed during operation and maintenance of the aerial work platform.

When handling the unit, in addition to the instructions in this manual, the user must also observe the local legislation, the guidelines stipulated by the employer, and regulations valid at the work site.

Dinolift Oy is constantly developing its products. For this reason, the contents of this manual might not always be in full compliance with the most recent version of the product. Dinolift Oy reserves the right to modify the product without prior notice. Dinolift Oy assumes no liability for any problems caused by changed or missing data or mistakes in this manual.

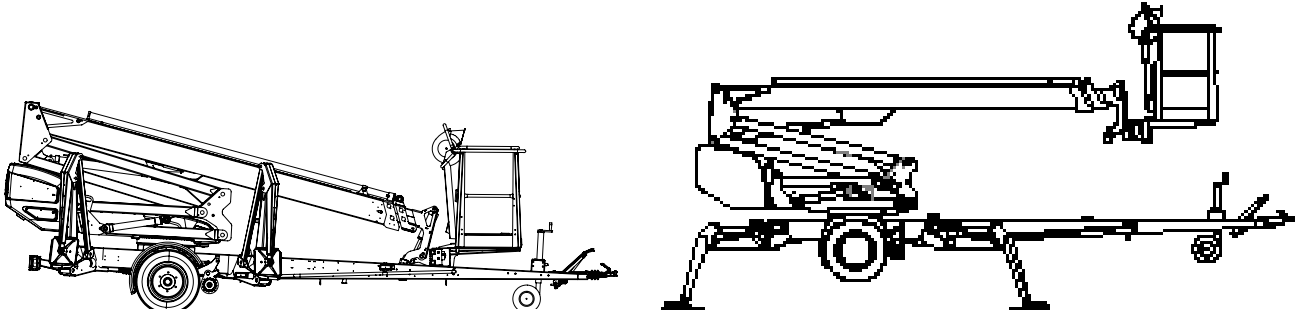
Please consult your dealer or the manufacturer for more information and detailed instructions.

1.1. OVERVIEW OF THE UNIT

This unit is a trailer mounted, towable aerial work platform.

It is an aerial work platform, which complies with the EN280 type 1, where travelling is only allowed with the platform in transport configuration.

For the operation the lift shall be supported by its hydraulic outriggers, extended so that the unit's wheels lift off the ground.



The lift's primary power source is a mains-powered electric motor. The outriggers and the boom system are hydraulically powered.

As an option, the lift has a pedestrian controlled driving device, which allows transport for short distances without a towing vehicle.

Consult the chapters "Technical data" and "Structure and functions of the work platform" in this manual for more detailed information about the lift.

1.2. INTENDED USE OF THE WORK PLATFORM

The aerial work platform is exclusively intended for transferring people and tools and acting as a work platform within its permissible load-bearing capacity and reach (refer to the "Technical Specifications" table and the "Reach Diagram").

The intended use also covers:

- Following all the instructions in the Operating Instructions
- Performance of the inspections and maintenance operations.

This aerial work platform is NOT insulated, and does not offer protection against contact with electric current. The aerial work platform must not be used for work on electric systems.

Observe the safety instructions concerning the operating environment, and the restrictions given in them,

NOTICE

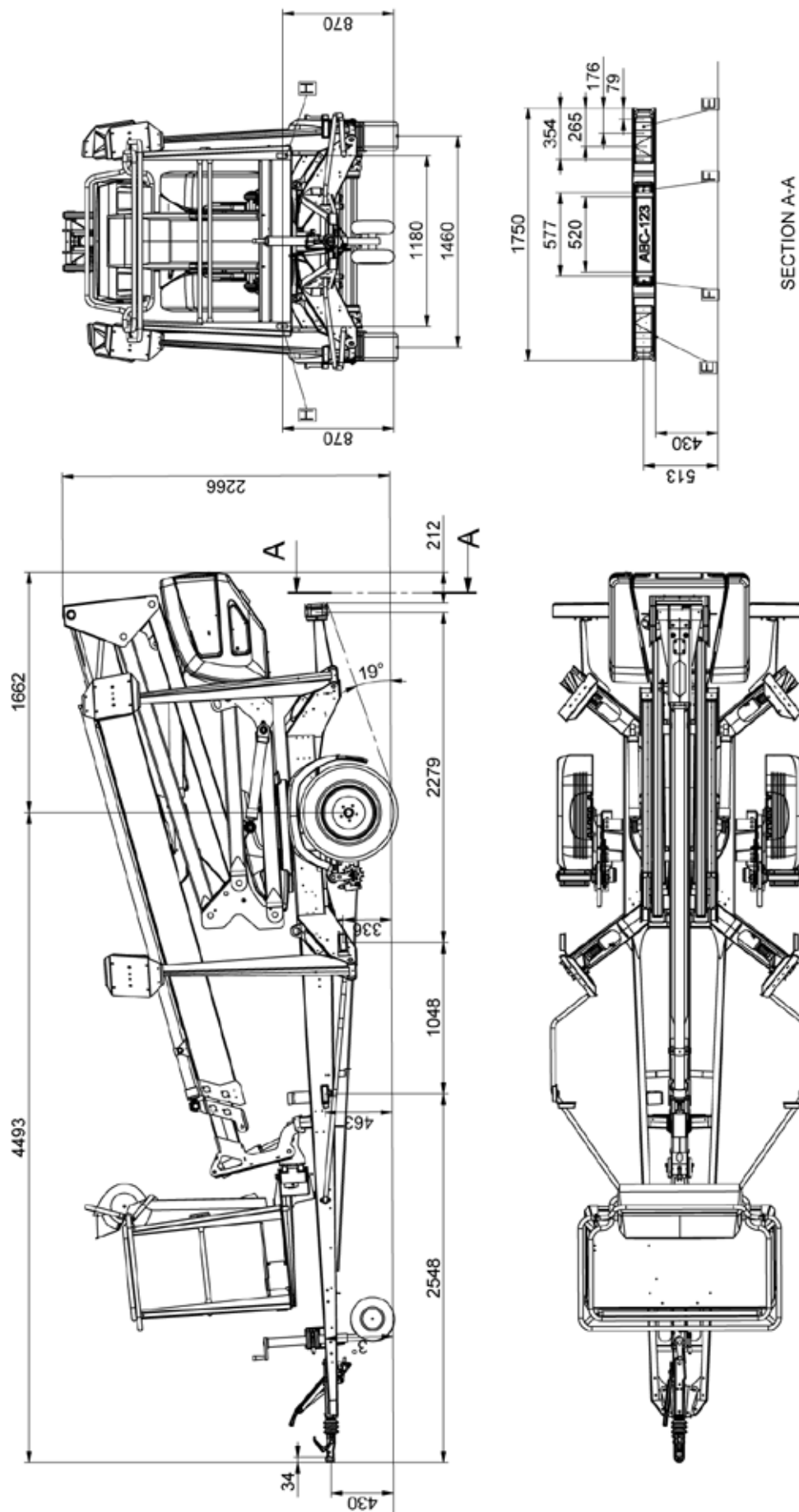
The operator must receive instructions and consent from the manufacturer for all such specific work methods or conditions that the manufacturer has not explicitly defined in the unit's operation and maintenance instructions.

2. TECHNICAL SPECIFICATION

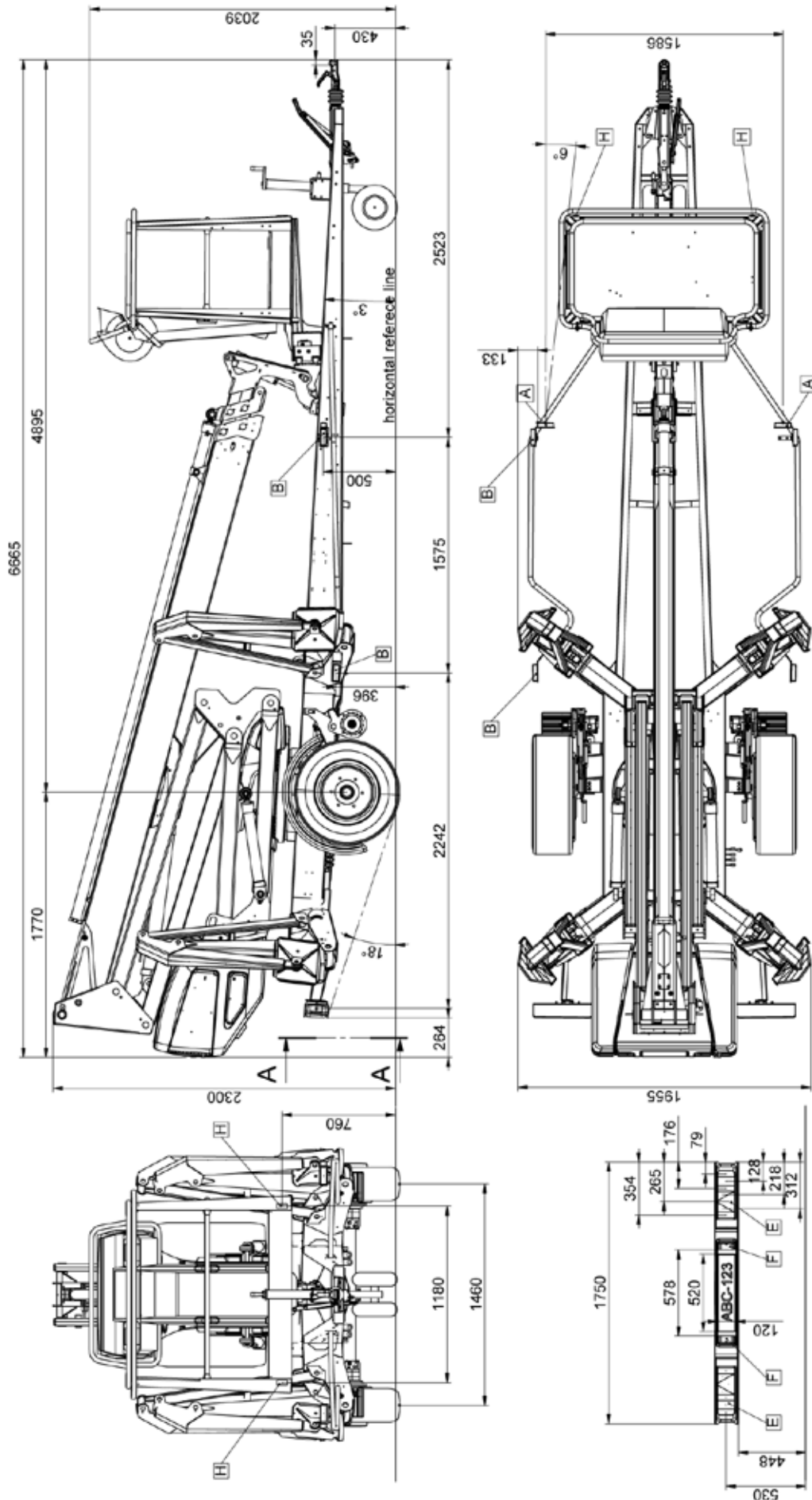
		160XT II	180XT II	210XT II
Max. working height		16,0 m	18,0 m	21,0 m
Max. platform height		14,0 m	16,0 m	19,0 m
Max. outreach		9,1 m	11,2 m	11,7 m
Boom rotation		continuous		
Platform rotation		180°		
Turn area		refer to the reach diagram		
Support width		3,80/4,20 m	3,90/4,30 m	3,90/4,30 m
Transport width		1,80 m	1,95 m	1,95 m
Transport length		6,12 m	6,63 m	7,92 m
Transport height		2,30 m	2,30 m	2,33 m
Weight (incl. Honda power unit)		1990 kg	2300 kg	2465 kg
Max. allowed load on platform		215 kg		
Max. number of persons + additional load		2 persons + 55 kg		
Max. allowed sideways load (caused by persons)		400 N		
Max. lateral inclination (chassis)		±0,3°		
Max. wind speed during operation		12,5 m/s		
Min. ambient temperature when working		- 20 °C		
Max. support force on the outriggers		16800 N	16800 N	22800 N
Platform size		0,7 x 1,3 m		
Gradeability		25%		
Power supply		0	0	0
- mains current		230V/50Hz/10A		
	Sound pressure level	< 70 dB		
	Whole-body vibration	Not detectable		
- petrol-driven power unit		Honda GX200SXE (Euro 2 / EPA Phase 3 / CARB Tier 3)		
	Net power	4.1 kW		
	Fuel tank volume	3,1 l		
	Fuel consumption	1,7 l/h		
	Sound pressure level	98 dB		
	Whole-body vibration	< 0,5 m/s ²		
- diesel-driven power unit		Hatz 1B30 (EPA / CARB Tier 4 Final)		
	Net power	4,4 kW (6 hv)/ 2800 r/min		
	Sound pressure level	101 dB		
Socket outlets on the platform		2 x 230V/50Hz/16A		

2.1. DIMENSIONAL DRAWINGS

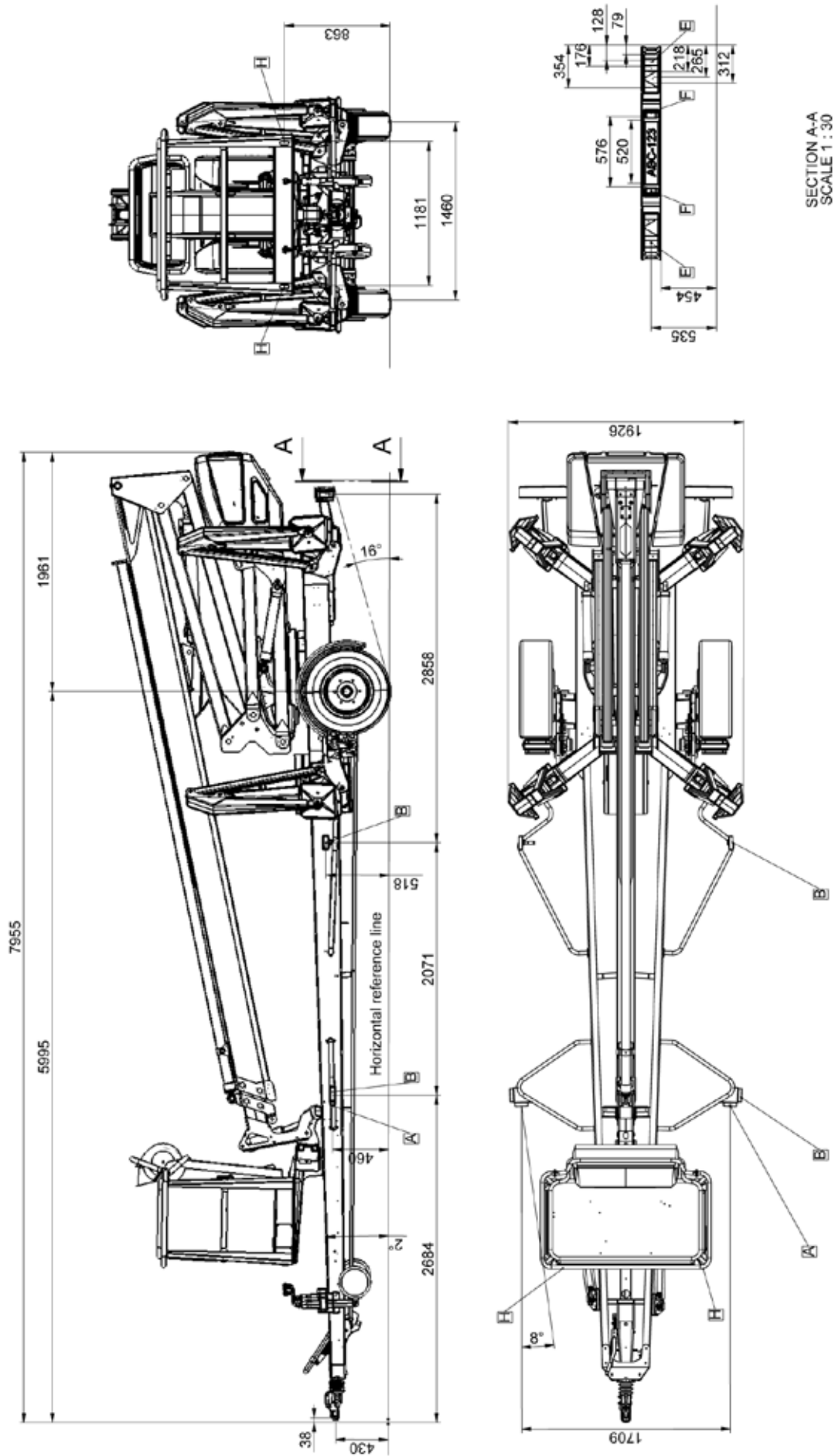
2.1.1. 160 XT II



2.1.2. 180 XT II

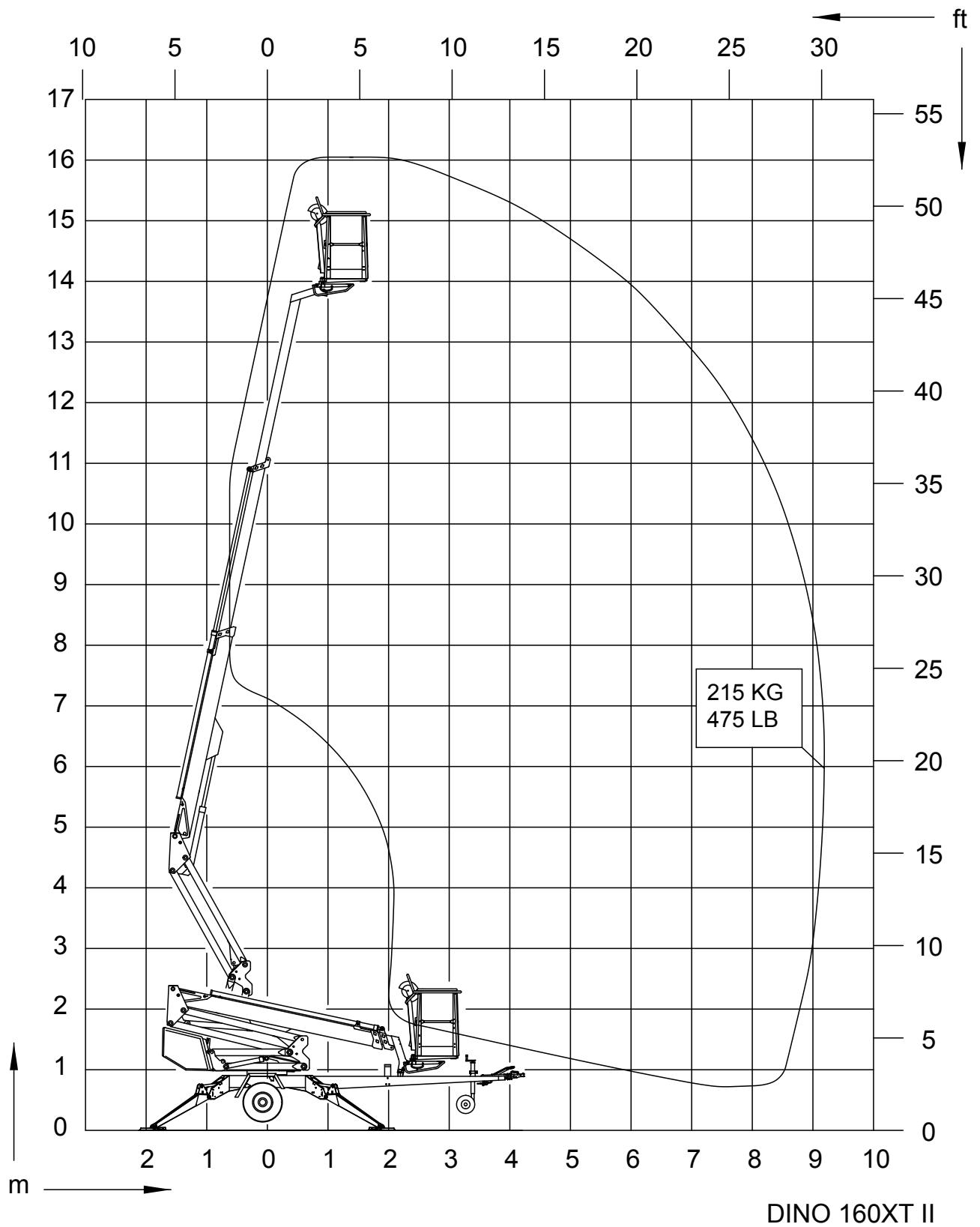


2.1.3. 210 XT II

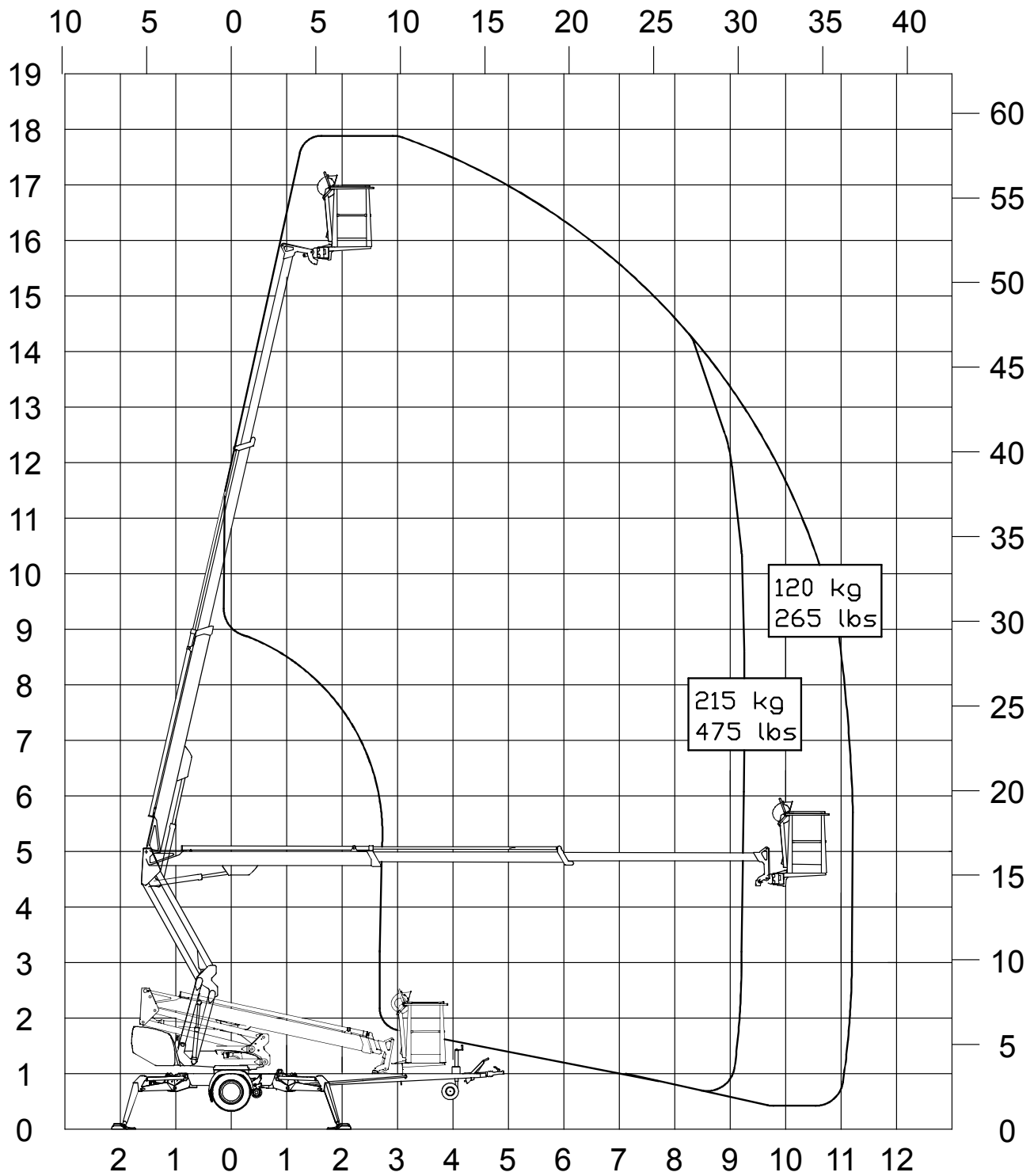


2.2. REACH DIAGRAM

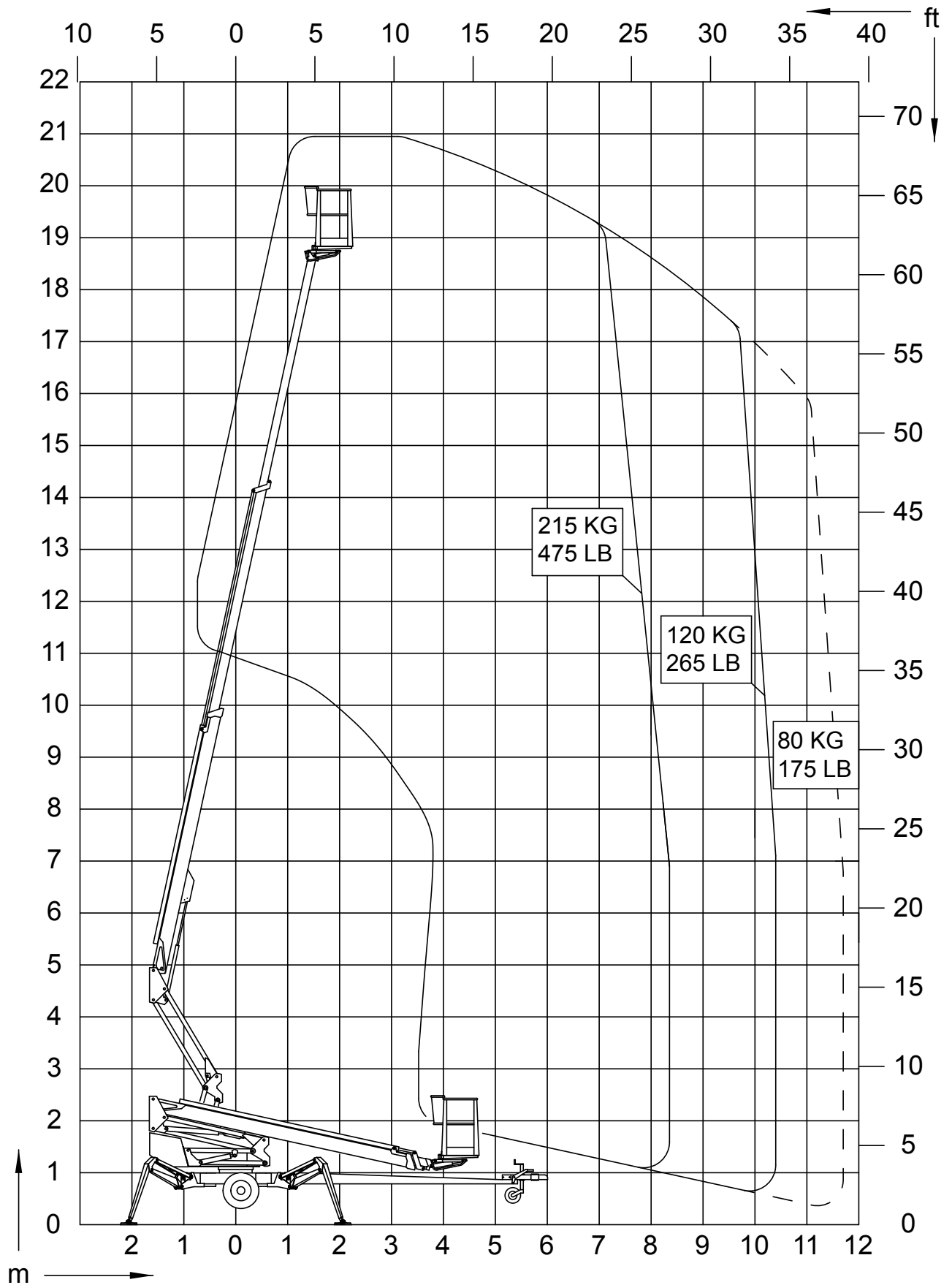
2.2.1. 160 XT II



2.2.2. 180 XT II



2.2.3. 210 XT II



2.3. EXAMPLE OF MACHINE'S NAMEPLATE

Every machine has a nameplate shown in the picture below. In the nameplate are marked the name and address of machine manufacturer, serial number of the machine and other relevant machine information.

Type	DINO		Manufacturer	DINOLIFT
Year of manufacture			Address of manufacture	Raikkolantie 145 32210 Loimaa FINLAND
Number of manufacture				CE
Weight kg			Max load	215 kg
Max load of persons	2		Additional load	55 kg
Max side force	400 N		Max inclination of chassis	0,3 °
Voltage	230 V		Frequency	50 Hz
Min operating temp.	-20 °C		Max wind force	12,5 m/s

The nameplate is located on the right side of the towbar as shown in the picture.

The serial number is also engraved in the chassis above the nameplate.



2.4. MODEL OF EC-DECLARATION OF CONFORMITY**EC-Declaration of Conformity for Machinery****Manufacturer**

Dinolift Oy
Raikkolantie 145
FI-32210 Loimaa, FINLAND

declares that

DINO 180XT II Access Platform no YGCD180XTF2030023

is in conformity with the provisions of Machinery Directive **2006/42/EC** as amended and with national implementing legislation.

Inspection according to 2006/42/EC appendix IX carried out by notified body nr. 0537

VTT
P.O.Box 1300
FI-33101 Tampere, FINLAND

which has granted the certificate No. **VTT 183/524/14**

Access platform also fulfils the requirements of the following EEC directives:

2006/95/EC, 2000/14/EC, 2004/108/EC

Measured sound power level L_{wa} (petrol/diesel) (96+1,5) 97,5 dB / (98,5+1,5) 100 dB
Quaranteed sound power level L_{wa} (petrol/diesel) 97,5 + 0,5 dB / 100+0,5 dB

2000/14/EC Conformity assessment procedure followed: Annex V: Internal control of production.

Following harmonized standards have been applied in designing the machine:

SFS-EN 280:2013; SFS-EN 60204-1/A1; SFS-EN-ISO 12100

Person authorized to draw up the Technical File: Santtu Siivola
Chief Engineer
Dinolift Oy, Raikkolantie 145,
32210 Loimaa, FINLAND

Loimaa 05.02.2015

Antti Tuura
Supervisor

2.5. MODEL OF INSPECTION PROTOCOL FOR THE ACCESS PLATFORM



TEST CERTIFICATE

DATE: 16.9.2014

www.dinolift.com

START-UP TESTS:

Inspection place: Dinolift Oy

Inspector's signature: _____

1074

Koivisto Pekka NT0153

BASIC KNOWLEDGE

Manufacturer: Dinolift OY

Place of manufacture: Finland

Address: Raikkolantie 145
32210 LOIMAA

Importer: _____

- | | | | |
|---------------|---|--|--|
| Type of lift: | <input checked="" type="checkbox"/> Boom platform | <input type="checkbox"/> Scissor platform | <input type="checkbox"/> Mast platform |
| Chassis: | <input type="checkbox"/> Car | <input type="checkbox"/> Self propelled | <input checked="" type="checkbox"/> Trailer mounted |
| Boom: | <input type="checkbox"/> Articulated boom | <input type="checkbox"/> Telescope boom | <input checked="" type="checkbox"/> Articulated telescope boom |
| | <input type="checkbox"/> Scissor | <input type="checkbox"/> Fixed mast | <input type="checkbox"/> Telescope mast |
| Outriggers: | <input checked="" type="checkbox"/> Hydraulic turning | <input type="checkbox"/> Hydraulic pushing | <input type="checkbox"/> Mechanical |

TECHNICAL SPECIFICATIONS

- | | | | |
|------------------------|---------------------------|--------------------------------|-----------------------|
| Machine and type: | <u>DINO 180XT II</u> | Max. platform height | <u>16 m</u> |
| Number of manufacture | <u>YGCD180XT E2030004</u> | Max. outreach: depend on load: | <u>Depend on load</u> |
| Year of manufacture | <u>2014</u> | | |
| Max. lifting capacity: | <u>215 kg</u> | Boom rotation: | <u>Continuous</u> |
| Max. person number: | <u>2</u> | Support width: | <u>3,8 m</u> |
| Max. additional load: | <u>55 kg</u> | Transport width: | <u>1,95 m</u> |
| Power supply: | <u>230VAC</u> | Transport length: | <u>6,65 m</u> |
| Lowest temperature: | <u>-20 °C</u> | Transport height: | <u>2,31 m</u> |
| Weight: | <u>2315 kg</u> | Basket size: | <u>0,7 x 1,3 m</u> |

Inspection points: (Y = meet standards N = do not meet standards)

- | | Y | N | | Y | N |
|--|-------------------------------------|--------------------------|--|-------------------------------------|--------------------------|
| A. STRENGTH | | | 6. Plate for supports | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 1. Certificate of material | <input checked="" type="checkbox"/> | <input type="checkbox"/> | 7. Safety colours | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 2. Certificate of strength | <input checked="" type="checkbox"/> | <input type="checkbox"/> | | | |
| B. STABILITY | | | D. SAFETY REQUIREMENTS | | |
| 1. Certificate of stability test | <input checked="" type="checkbox"/> | <input type="checkbox"/> | 1. Indicating device for horizontal position | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 2. Working space diagram | <input checked="" type="checkbox"/> | <input type="checkbox"/> | 2. Locking device and lockings | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| C. GENERAL REQUIREMENTS | | | 3. Stop device for lifting | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 1. User's manual | <input checked="" type="checkbox"/> | <input type="checkbox"/> | 4. Stop for opening of support | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 2. Place for safekeeping for user's manual | <input checked="" type="checkbox"/> | <input type="checkbox"/> | 5. Safety distances | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 3. Machine plate - checking plate | <input checked="" type="checkbox"/> | <input type="checkbox"/> | 6. Position of working face | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 4. Load plate | <input checked="" type="checkbox"/> | <input type="checkbox"/> | 7. Structure of working face | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 5. Warning plate | <input checked="" type="checkbox"/> | <input type="checkbox"/> | 8. Emergency descent system | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| | | | 9. Limit devices | <input checked="" type="checkbox"/> | <input type="checkbox"/> |

E. ELECTRIC APPLIANCES 1. Electric appliances <input checked="" type="checkbox"/> <input type="checkbox"/>	G. SAFETY DEVICE 1. Safety limit switch <input checked="" type="checkbox"/> <input type="checkbox"/> 2. Sound signal <input checked="" type="checkbox"/> <input type="checkbox"/>
F. CONTROL DEVICES 1. Protections <input checked="" type="checkbox"/> <input type="checkbox"/> 2. Symbols / directions <input checked="" type="checkbox"/> <input type="checkbox"/> 3. Placings <input checked="" type="checkbox"/> <input type="checkbox"/> 4. Emergency stop <input checked="" type="checkbox"/> <input type="checkbox"/>	H. LOADING TEST 1. Overload test = 323 kg (150%) <input checked="" type="checkbox"/> <input type="checkbox"/> 2. Funktional test = 237 kg (110%) <input checked="" type="checkbox"/> <input type="checkbox"/>
FAILINGS AND NOTES	
Failings have been repaired. Date: _____ Signature: _____	

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Dino access platforms are subjected to an overload test and structural and functional inspection for the first time at the factory by the manufacturers authorized inspector. This is a model of a test certificate that is drawn up based on the inspection and delivered with the platform.

Keep this certificate and all other inspection documents with the platform stored in the place reserved for them for a minimum of 5 years.

3. SAFETY

This part describes all relevant warnings and safety rules and instructions regarding transport, operation and maintenance of the access platform.



DANGER

Failure to obey the operation, maintenance or safety instructions in this manual will result in death or serious injury. Read and understand all safety rules, operating instructions and machine labels and obey them.

Make sure that you understand all the safety instructions. Also make sure that others operating the machine or working in the work platform are familiar with these instructions

3.1. SAFETY INSTRUCTIONS

GENERAL

The operator of the lift must:

- be specially trained
- have authorisation in writing from the employer
- be well familiarised with the device
- be at least 18-years old

Keep the lift clean of any dirt which may impair the safe operation and impede the inspection of the structures.

The device must be serviced and inspected regularly.

Only skilled persons who are familiar with the service and reparation instructions are allowed to carry out the service and reparation work.

It is strictly prohibited to use a lift which is out of order.

Never disable the operation of any safety device or remove any safety devices or covers.



WARNING

The device must neither be altered without the manufacturer's consent nor be used under conditions which do not meet the requirements set by the manufacturer.

The operator must be given instructions and consent from the manufacturer for all such specific work methods or conditions, which the manufacturer has not explicitly defined

TRANSFERS

Observe the maximum allowed gradient during transfer of the lift. During transfer on rough terrain, try to stay above the machine.

Beware of fixed or moving obstacles in the terrain or near the lift while driving. Make sure that you have a clear view of the driving path.

WORK AREA AND PREPARATION FOR LIFTING

When working in busy areas the operating range of the lift must be clearly marked either by using warning lights or fencing.

Also observe the regulations of local road traffic laws.

Ensure the unobstructed range of movement before operating the outriggers.

The load-bearing capacity and the gradient of the base must be taken into account when supporting the chassis.

Ensure that the outriggers cannot slide while on a gradient.

Additional support plates of adequate size must be used under the outriggers when working on soft ground. Only use such additional support plates on which the metallic outriggers will not slide. While in the support position, ensure that the wheels are off the ground.

Always verify the horizontal position of the machine.

Always ensure that the work area is clear of outsiders. Danger of getting squeezed between rotating and fixed structures

While operating the boom from the control panel on the turning device, beware of getting pressed against the outriggers or other structures that do not turn with the boom.

LIFTING AND WORKING IN THE PLATFORM

Before operating, always ensure that the safety devices and the emergency descent system are in working order.

Never use a lift alone. Make sure, there is always someone on the ground, who can call for help in case of an emergency.

The max. allowed load on the platform is two (2) persons and at maximum fifty five (55) kg of additional load, however, the total load must not exceed two hundred fifteen (215) kg.

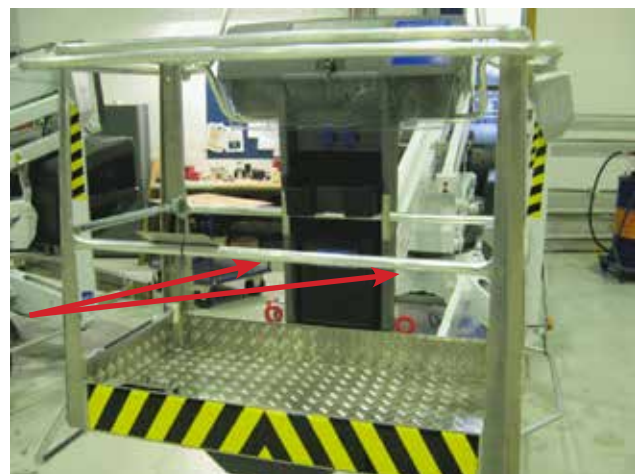
The lift **MUST NOT** be used as a crane

Use a safety harness while on the platform!

Do not use ladders, steps or other similar equipment on the platform.

Never add load onto the platform while in the upper position.

Never throw any objects from the platform.



The lift must not be used for transferring goods or persons between different floors or working levels. Stepping on or off the platform in motion is prohibited.

When the boom is in its lowest positions, make sure it cannot clash during rotation with structures that do not turn with the boom.

Always make sure before lowering the platform that the area on the underside is clear of any obstructions.

Avoid damaging the platform by lowering it on the ground or bringing it in contact with any structures.

OPERATING CONDITIONS

While operating, take into account climatic factors, such as wind, visibility and rain, so as not to endanger the safe operation of the lift.



The use of the lift is prohibited if
the temperature drops under - 20 °C or
the wind speed exceeds 12.5 m/s

Wind speed (m/s)		Conditions on land
0	Calm	Smoke rises vertically
1-3	Light air	Wind motion visible in smoke and felt on exposed skin. Leaves rustle.
4-7	Gentle breeze	Leaves in constant motion and smaller branches begin to move. A flag flies straight. Wind raises dust and loose paper.
8-13	Strong breeze	Smaller trees sway and large branches are in motion. Wind whistles in houses and other obstacles. Umbrella use is difficult.
14-16	Moderate gale	Whole trees in motion. Effort is needed to walk against the wind.

Do not take tools/material of large surface area onto the platform. The increase in wind load may jeopardize the stability of the device.

Beware of the live aerial power lines in the area - observe the minimum safety distances:

Voltage	Min. distance below (m)	Min. distance at the side (m)
100 - 400 V hanging spiral cable	0,5	0,5
100 - 400 V open-wire cable	2	2
6 - 45 kV	2	3
110 kV	3	5
220 kV	4	5
400 kV	5	5

3.2. SAFETY MESSAGES

The following safety alert symbols and safety signal words are used in this manual.

Obey all safety instructions that follow these symbols, in order to avoid dangerous situations and personal injuries.



This is a general safety alert symbol and it is used to alert you to a potential hazard. Obey all safety messages that follow this symbol.



DANGER

Red DANGER-message indicates a hazardous situation which, if not avoided, will result in death or serious injury



WARNING

Orange WARNING -message indicates a hazardous situation which, if not avoided, could result in death or serious injury.



CAUTION

Yellow CAUTION -message indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.

NOTICE

Blue notice-message is used to bring your attention to special notifications or instructions relating to operation or maintenance of the lift. These messages include instructions to avoid property damages and material losses or to increase reliability and safe operation of the lift.

3.3. SAFETY DEVICES

1. Support outriggers (Fig. A)

The safety limit switch RK3 prevents the operation of the outriggers and the driving device when the boom is not resting on the transport support. The switch is located on the tow-bar at the transport support.

2. Lifting the boom (Fig. B)

The lift's all support outriggers must be in the support position before the boom is lifted. Make sure that the wheels are off the ground.

The safety limit switches RK11, RK12, RK13 and RK14 are located on the support outriggers.

3. Overload protection switches (Figs. A and C)

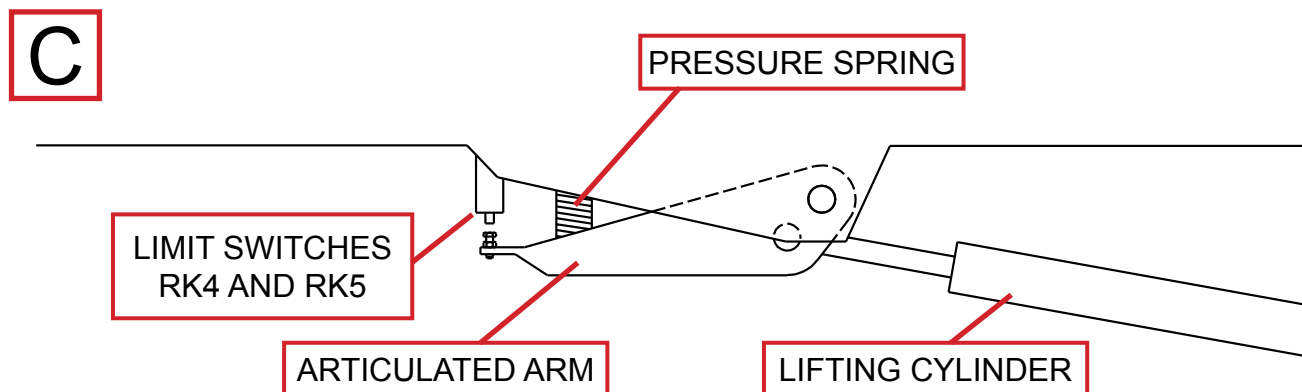
The safety limit switches prevent overloading of the lift. At a predetermined position, the overload limit switch RK4 stops the extension of the telescope and the lowering of the boom. The overload limit switch RK5 backs up, if the RK4, for some reason, does not work. The green light in the control centre on the platform is lit, when the platform is within the allowed operating range. The red light will illuminate as soon as the RK4 stops the movement. When the red light is illuminated, the lift can be operated in the direction, where it stays inside the permitted outreach area. The safety limit switch RK5 backs up the operation of the RK4, and at the same time, switches on the buzzer on the platform.

4. Depressing the emergency stop button, stops all the movements immediately and turns off the power unit.

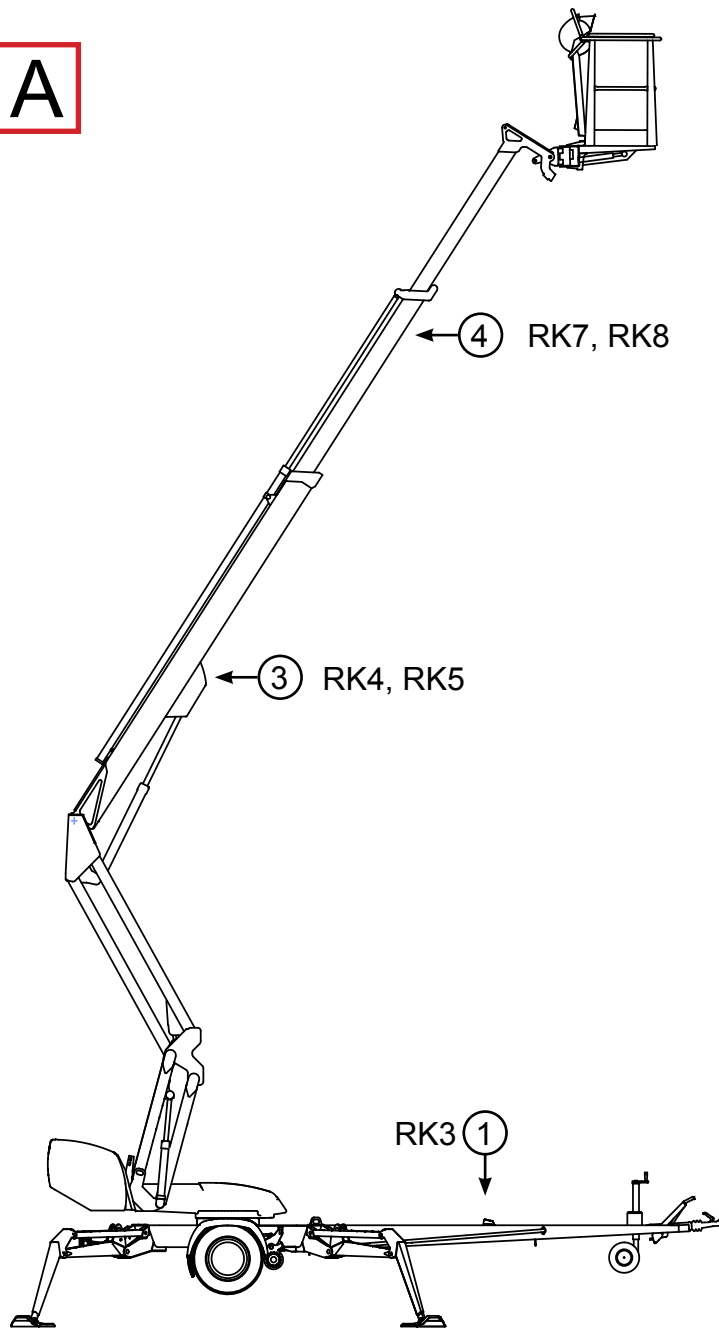
NOTICE

The emergency stop button must be pulled up before starting the power unit.

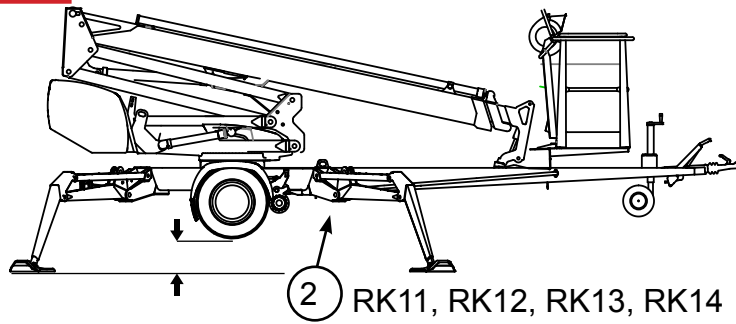
Ensure the operation of the safety devices – do not lock the cover of the chassis control centre with key while the lift is in operation.



A



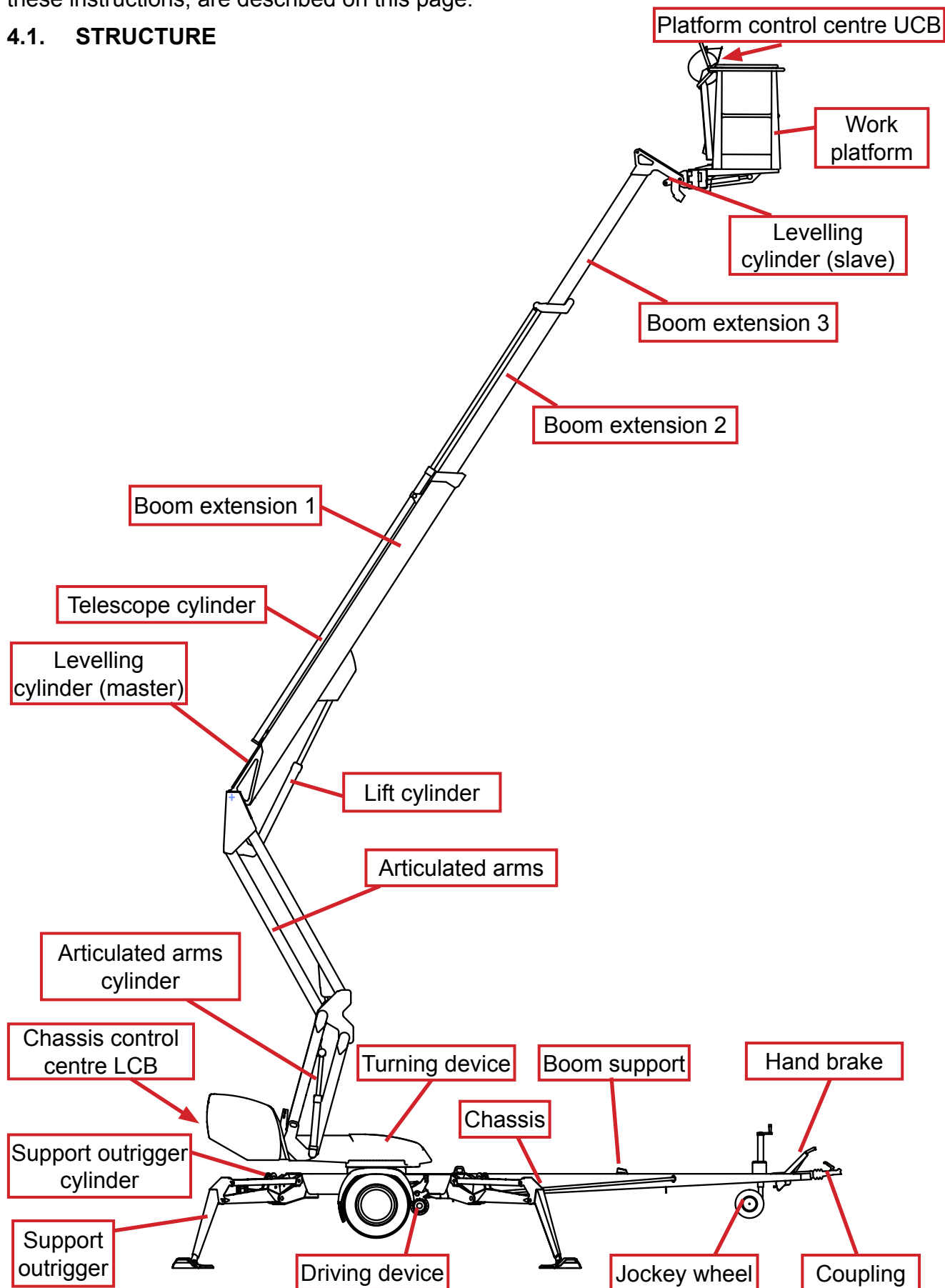
B



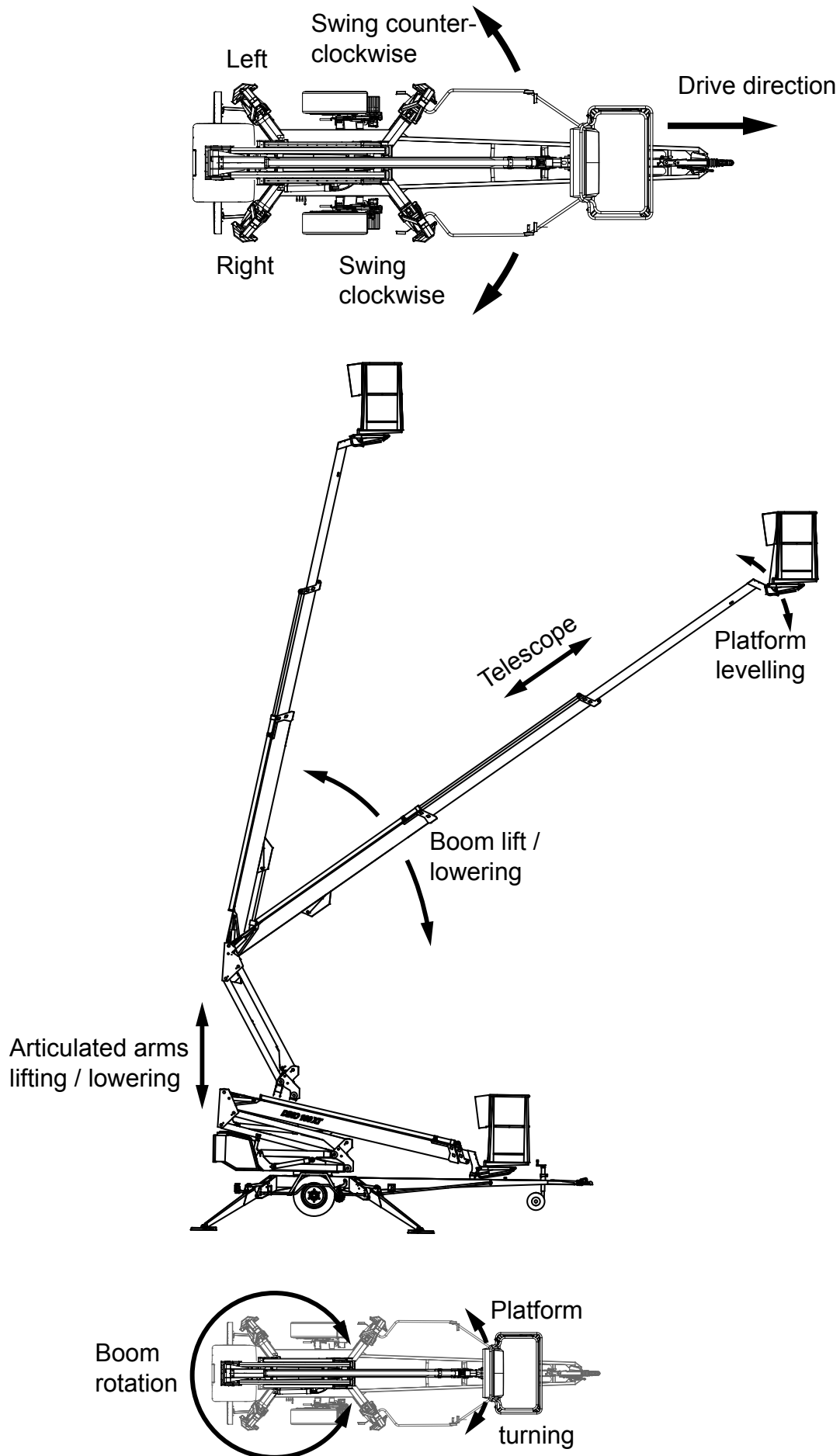
4. BASIC STRUCTURE AND FUNCTIONS

The denominations of the machine's essential parts and concepts, which are used later in these instructions, are described on this page.

4.1. STRUCTURE



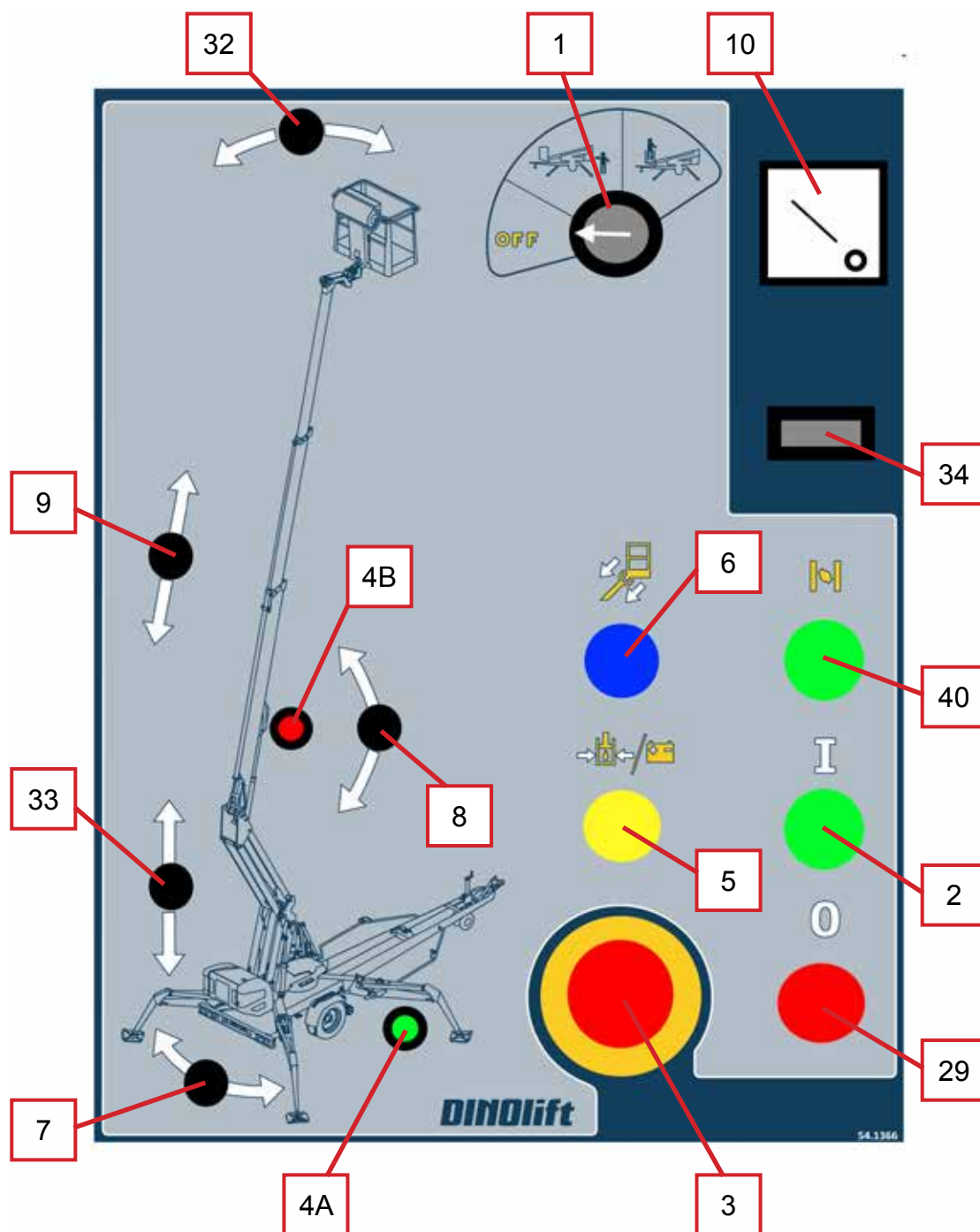
4.2. BASIC FUNCTIONS



4.3. OPERATING CONTROLS

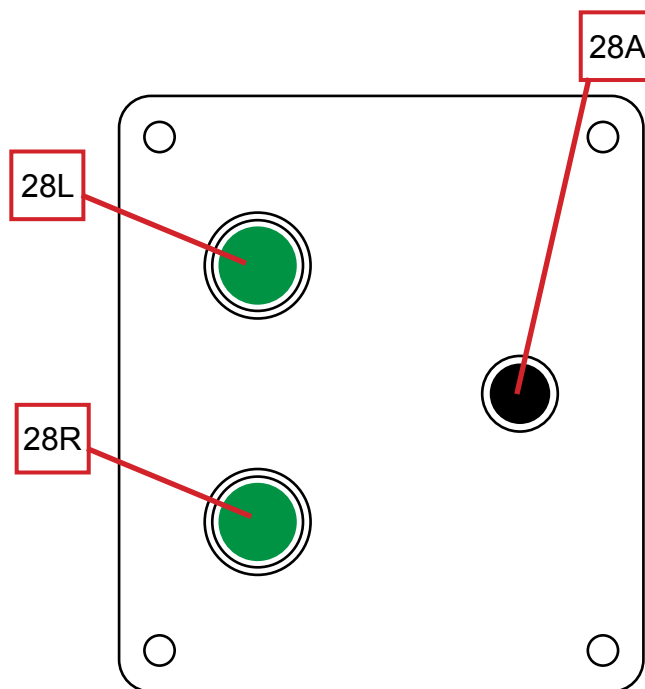
4.3.1. Operating controls in chassis control centre LCB

1	Selector switch	7	Lever switch for turning
Q1.1	OFF-power off	8	Lever switch for boom system
Q1.2	LCB-control centre – outriggers – hydraulic drive	9	Lever switch for telescope
Q1.3	UCB-platform control centre	10	Voltage meter
2	Start button	29	Stop button
3	Emergency stop	32	Lever switch for levelling of platform
4A	Signal light for the outrigger limit switch	33	Lever switch for articulated arms
4B	Signal light for safety device (RK5)	34	Hour meter
5	Start button for emergency descent system	40	Choke
6	Pushbutton for retracting the telescope		



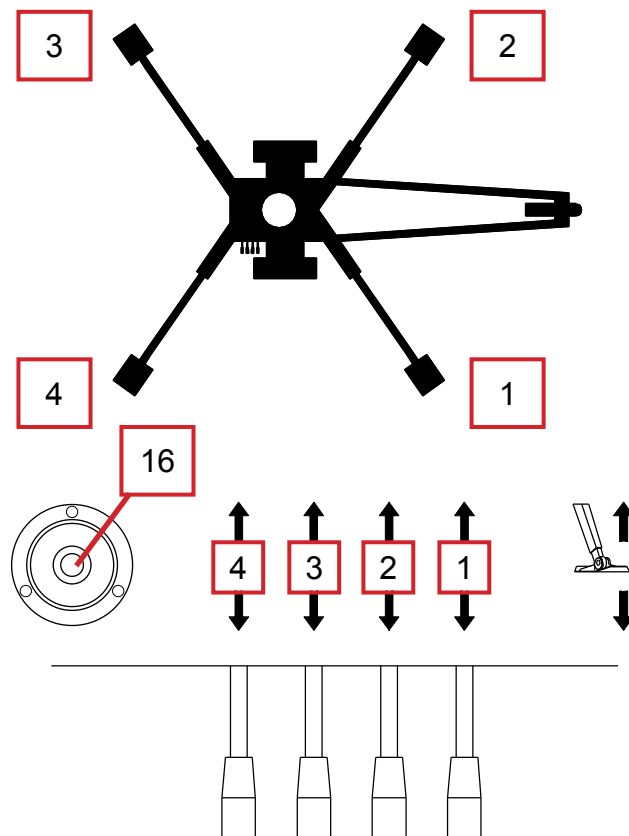
4.3.2. Operating controls of drive system

28A.	Forward - backward
28A + 28L	drive to the left
28A + 28R	drive to the right



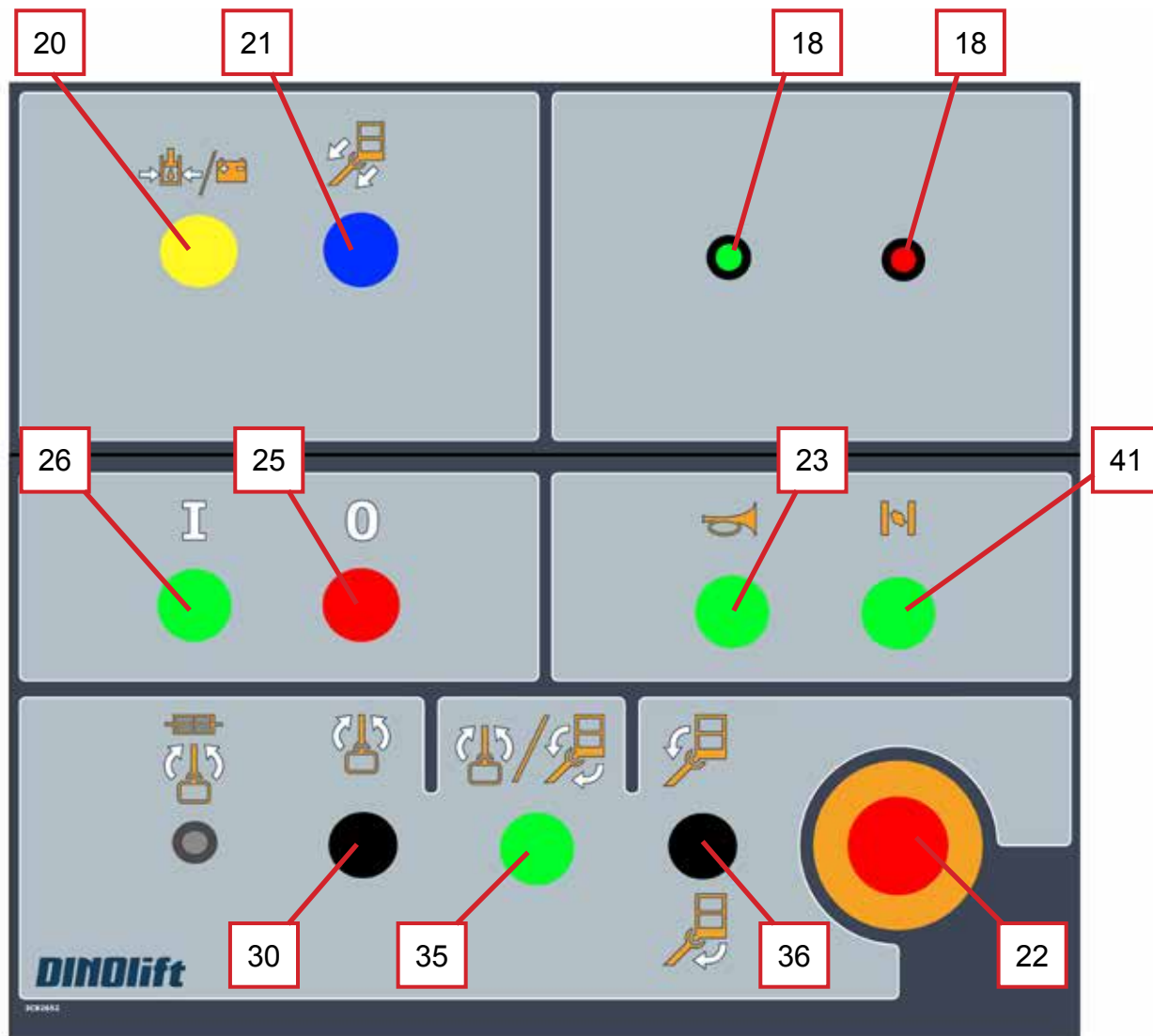
4.3.3. Operating controls of outriggers

1	Front outrigger, right
2	Front outrigger, left
3	Rear outrigger, left
4	Rear outrigger, right
16	Position indicator of chassis



4.3.4. Operating controls in platform control centre UCB

Close the cover of the chassis control centre before operating the controls on the platform.
The cover must not be locked while the lift is in operation.

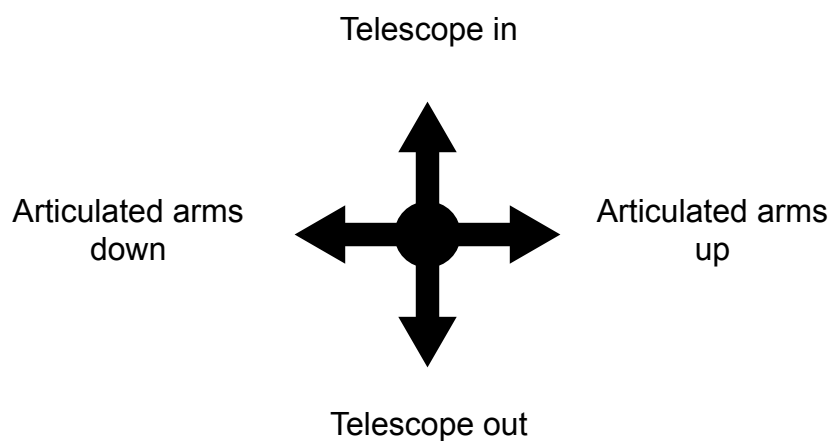
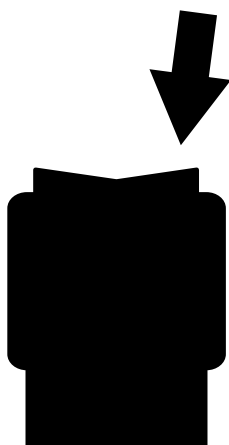
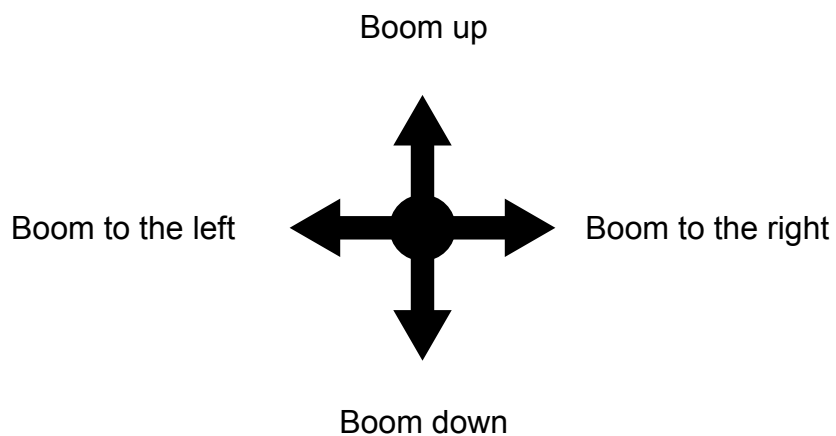


18	Signal lights	25	Stop button for the engine
	Green – inside the allowed outreach range	26	Start button for the engine
	Red – at the border of the allowed outreach range	30	Lever switch for turning the platform
20	Start button for the emergency descent system	35	Dead-man-button
21	Pushbutton, retracting the telescope	36	Lever switch for levelling the platform
22	Emergency stop	41	Choke
23	Sound signal button		

17. Control lever



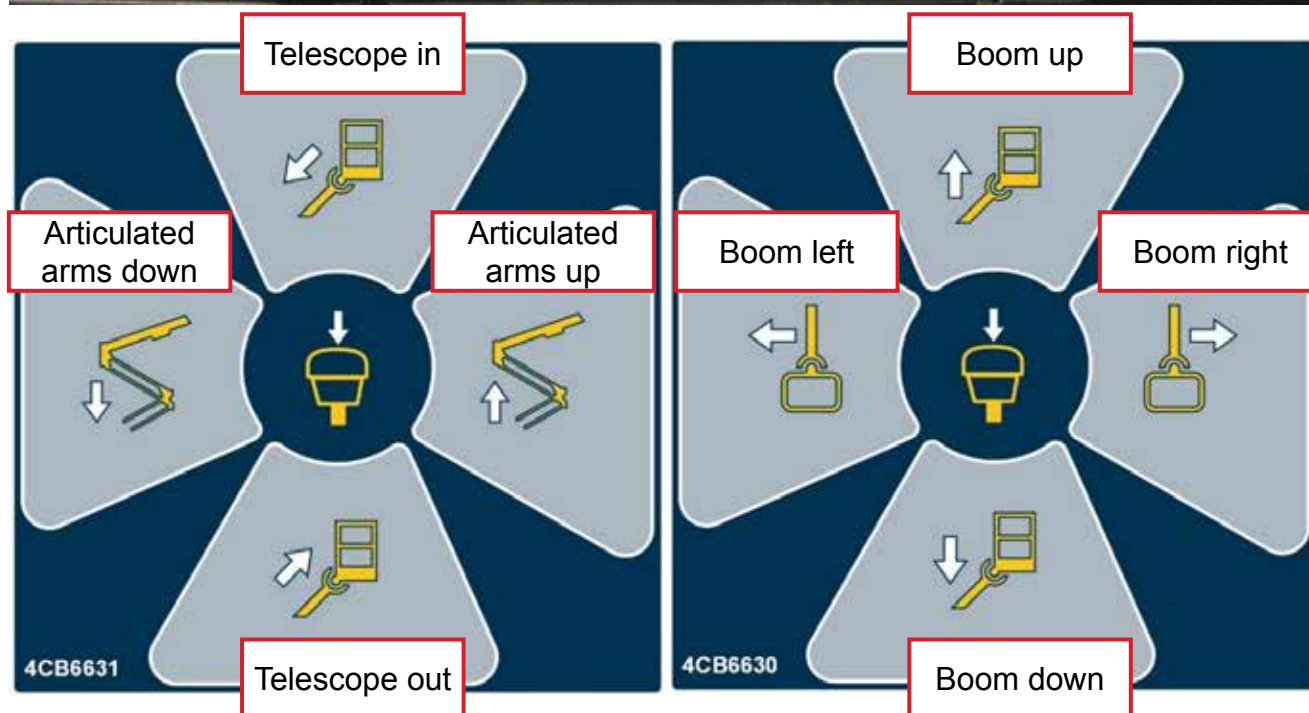
The functions to be controlled are selected using the "dead-man-buttons" at the end of the joystick. Always press the button first, and only after that, turn the handle. The safety connection prevents the movements, if the handle is turned before depressing the button.



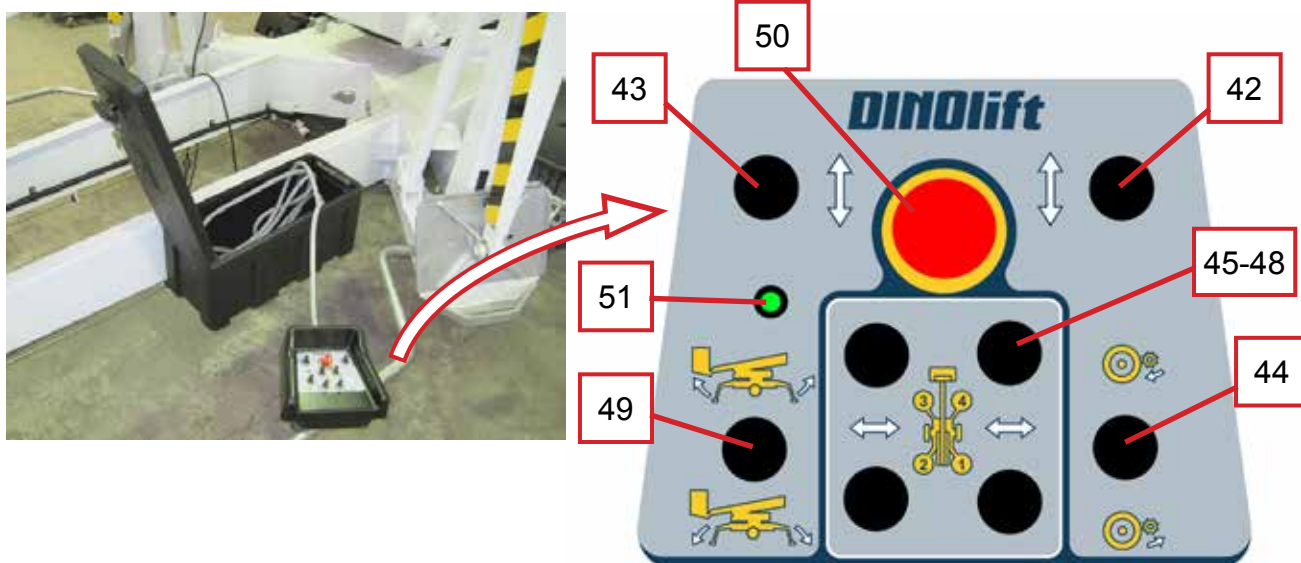
4.3.5. Setup with two control levers (option)

Platform control centre UCB can be fitted with two control levers as an option.

Right and left control lever (17 right/left) replace the normal control lever (17). Different functions are selected by turning the joystick in the desired direction of movement. Always press the button first, and only after that, turn the handle. The safety connection prevents the movements, if the handle is turned before depressing the button.



4.4. AUTOMATIC LEVELLING AND ELECTRIC CONTROL OF DRIVING DEVICE – DCB CENTRE (OPTION)



42	Lever switch for driving, right (to the front-rear)	49	Lever switch for automatic levelling
43	Lever switch for driving, left (to the front-rear)	50	Emergency stop
44	Depressing the driving device rollers (option)	51	Light for automatic levelling
45-48	Lever switches for outriggers 1-4		

5. OPERATING INSTRUCTIONS

5.1. START-UP

NOTICE

Before operating the lift, perform all daily maintenance measures listed in the maintenance schedule.

The operator must do a worksite inspection and daily maintenance:

- at the beginning of each workday
- before operating the lift at a new worksite
- when the operator changes in the middle of a workday

5.1.1. Worksite inspection

1. General information

- Is the lift suited for the intended job?
- Is the performance of the lift sufficient for the job? (reach, loadability etc.)
- Is the position of the lift safe?
- Is the lighting on the worksite sufficient?

2. Documents

- Are the Operation and Service Instructions for this lift present? (Manufacturer's instructions)
- Are inspections and servicing carried out in accordance with the instructions and have the defects affecting the safety been checked as repaired?
- (Inspection protocols)

3. Structure (Visual inspection and operational test)

- General condition of the lift
- Operation and protection of the controls
- Emergency stop, signal horn and limit switches
- Electrical appliances and wiring
- Oil leaks
- Load markings and signs

4. Operator

- Is the operator old enough?
- Has the operator received the required training?

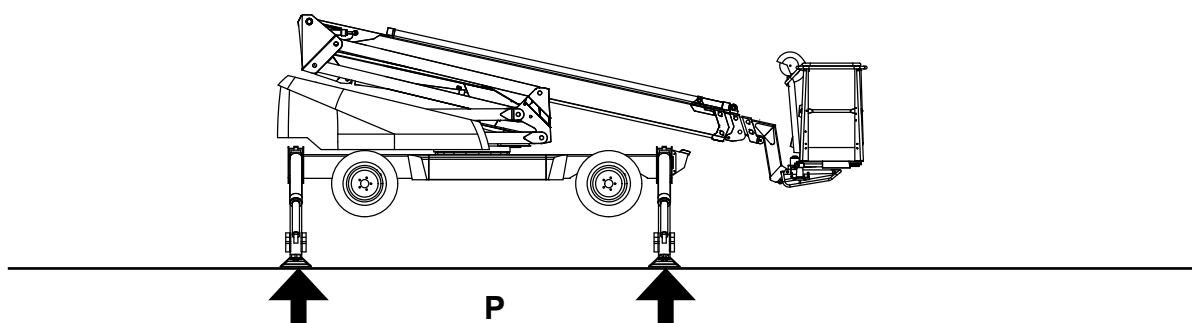
5. Special issues on the worksite

- Are there any additional regulations relevant to the worksite or the work?

5.1.2. Positioning the lift

1. make sure that the ground is even and hard enough to support the lift in a steady, level position.

Soil material	Density	Max. ground pressure P kg/cm ²
Gravel	High density	6
	Medium density	4
	Loose	2
Sand	High density	5
	Medium density	3
	Loose	1,5
Fine sand	High density	4
	Medium density	2
	Loose	1
Sand / mud	High density (very hard to work)	1,00
	Medium density (hard to work)	0,50
	Loose (easily worked)	0,25



DANGER

If the ground is soft, use sufficiently large and sturdy additional plates under the support outriggers.

2. Drive the lift to the inspected lifting site
3. Engage the parking brake
4. Disconnect the lift from the towing vehicle

5.1.3. Connecting the power supply to the lift

A. POWERED BY AC-SUPPLY

While the mains voltage is plugged in, the operating voltage of 12 VDC is supplied by a power source.

- connect the mains cable to the power supply
- switch on the main current switch 52
- with the electric motor at maximum load, the voltage must be 230 VAC (-10%/ +6%), the frequency 50 Hz, and rating of the fuse 10A (the length of the connecting cable has some effect)

B. POWERED BY COMBUSTION ENGINE (OPTION)

In the absence of mains current, the operating voltage of 12 VDC is supplied by a battery.

- do not connect the mains cable (230 VAC)
- switch on the main current switch 52
- open the fuel cock
- switch on the choke for the start by depressing the button on the cover of the centre

If the battery is flat, start the power unit by pulling the starter grip, and at the same time, keeping the button at the power unit's bed depressed. Pull the starter grip lightly until you feel resistance, then pull briskly. Do not allow the starter grip to snap back against the engine.

Leave the combustion engine running between the operations, because the battery will not be recharged, unless the combustion engine is running.



**Close the fuel cock when stopping the combustion engine.
The fuel cock must be closed during towing of the lift.**

B. POWERED BY DIESEL ENGINE (OPTION)

- do not connect the mains cable (230 VAC)
- switch on the main current switch 52
- Refer to the separate user manual for the diesel engine, delivered with the lift, for instructions about starting up the engine, when the battery is flat.
- Leave the combustion engine running between the operations, because the battery will not be recharged, unless the combustion engine is running.

To avoid damaging the electronic devices, do not connect the mains cable while the diesel engine is running.

To access the operating controls, open the LCB centre cover on the turning device

Check the condition of the battery to ensure the operation of the emergency descent system. Depress the yellow button (5), and simultaneously, retract the telescope using the lever switch (9). Then the emergency descent motor must not stall.



CAUTION

Use ear protection while using the lift with a petrol engine or diesel engine. Sound pressure level at chassis control centre: 98 dB.

5.1.4. Starting up

1. Turn the selector switch (1) to position "LCB centre".
2. Start the engine by depressing the button 2 (green).

The electric timer of the lift automatically disconnects the supply voltage (12 VDC) in about 1 hour after the electric motor or the combustion engine has been turned off.

Re-activate the power supply by pressing the start button either in the chassis control centre or in the platform control centre.

Petrol engine:

- turn off the choke
- adjust the engine speed

5.1.5. Levelling the lift

1. Lower the front support outriggers 1-2 (on the tow-bar side)
2. Lower the rear support outriggers 3-4 (do not damage the jockey wheel).
3. Level the chassis with the outriggers with the help of the level gauge (16). The air bubble must be located inside the inner ring.
4. the signal light (4A, green) in the chassis control centre LCB is illuminated, when all the outriggers are in the support position and the limit switch circuit of the outriggers is closed

Levelling with the automatic levelling (option)

1. Lower the outriggers from DCB control centre using the lever switch 49.
The automatic levelling function positions the outriggers on the ground and levels the chassis. The signal light 51 will flash as long as the levelling is in progress.
2. Switch 49 must be kept depressed throughout the levelling. If the lever is released, the operation will be interrupted. The levelling can be resumed by turning the lever anew.
3. The signal light 51 will remain lit once the function has been successfully completed.

Before using the lift, check that:

- the chassis is level
- the wheels are clearly off the ground
- all outriggers are firmly supported on the ground

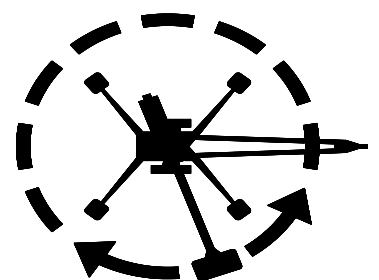
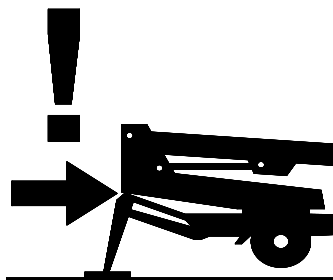


DANGER

The operation is prohibited if the lift is not properly supported and in a level position. observe the effect of ice, possible rain and inclination of the surface on the support (the support outriggers must not slip on the surface).

NOTICE

If you have levelled the chassis of the lift ON A GRADIENT, turn the boom around carefully in the lower position to make sure that the boom does not bang against the support outriggers or other obstacles.



5.2. INSTRUCTIONS FOR WORKING



WARNING

Do all daily maintenance tasks and operational inspections stated in the maintenance manual before operating the lift. **Failure to check the correct functioning of safety devices may cause serious injury or make the consequences of an accident worse.**

All malfunctions in safety devices must be repaired before operating the lift

5.2.1. Operating the lift from the chassis control centre LCB

Turn the selector switch (1) to position "chassis control centre LCB".

- Lift the platform from the tow-bar and turn it to the side so that you can lower the boom. Extend the telescope if necessary to ensure that stepping onto the platform is safe.
- Drive the boom functions from control levers 7, 8, 9, 33 and the platform from lever 32

NOTICE

Do not damage the tow-bar jockey wheel!

The boom movements are noticeably slower when the emergency descent system is used. The speed of the boom movements cannot be adjusted continually with the control levers when the lift is operated from the chassis control centre.

5.2.2. Operating the lift from the platform control centre UCB

1. Lift the platform from the tow-bar and turn it to the side so that you can lower the boom. Extend the telescope as much as is necessary to ensure that stepping onto the platform is safe.
2. Turn the selector switch (1) to position "Platform control centre UCB", and take away the key. Do not lock the protective cover of the chassis control centre.
3. Start the normal operation of the lift
Step on the platform and drive the boom and platform movements as follows
 - Start the engine via the pushbutton 26.
 - Drive the boom system using the lever 17 in the platform control centre, and the work platform using the lever switches 30 and 36.
 - If possible, keep the telescope short while lifting and lowering movements.
 - To operate the movements of the boom system, press first the rocker switch 17 at the end of the control lever, and after that, move the control lever carefully in the desired direction of movement of the boom. If you move the lever before pressing the rocker switch, the action is deterred. The movement speed of the platform can be continually adjusted using the control lever 17

- Moving the platform via the lever switches 30 and 36 requires that the dead-man-button 35 be depressed simultaneously.
- The engine is switched off via the pushbutton 25.
(See point “Operating controls in platform control centre UCB”)

**WARNING**

Do not add load (e.g. another person) onto the platform, while the red overload light (18) is illuminated.

Measures to be taken after an event of overloading: Retract the platform to inside the operating range of the RK4 by depressing the “telescope in” button (6 or 21)(the green light will be illuminated) – after this, the lift may be operated normally

Example: A person, who is working alone on the platform, extends the telescope, or an empty platform is driven from the chassis control centre to the maximum reach, keeping it close to the ground. If the overload signal light will light up after this, it is not allowed to take any additional load onto the platform before the telescope has been retracted

4. With the boom slightly lifted and the telescope extended, make sure that the platform does not lower by itself while the operating controls are not being used.
5. Move the platform to the work object

**CAUTION**

The platform, buildings around it and other obstructions may cause a crushing hazard. Hands and legs must be kept inside the work platform at all times when moving the platform. Beware of obstacles above the platform.

Start/stop automation

The start/stop automation is operational, when driving from the platform control centre UCB. The operation is started by depressing the rocker switch at the end of the control lever 17 to start the engine. After that, turn the control lever 17 carefully in the desired direction of movement of the boom. The engine will stop automatically in about 3 seconds after the movement of the boom has stopped. The engine will restart as soon as the dead-man-switch is depressed, and the desired movement of the boom is resumed.

IF THE SAFETY DEVICES OR THE EMERGENCY DESCENT SYSTEM ARE NOT WORKING, HAVE THEM REPAIRED BEFORE OPERATING THE LIFT.

The platform movements can be operated with continually adjustable speed from the platform control centre (not from the chassis control centre). Only one movement can be operated at a time. If several control levers are operated simultaneously, only the movement with the least resistance will operate.

Observe when lifting the platform

- the operating range of the platform depends on the load (see “Technical Data”) and is monitored by the safety limit switches RK4 and RK5, which are located under the protecting cover
- The limit switches must not be adjusted or modified. The inspection and adjustment may only be carried out by an authorized serviceman.

Working in the same position for a long time

- there are pushbuttons for both stopping and starting in both the platform and the chassis control centres
- When the weather is warm, and the platform is kept for a longer period in the same position, it is not necessary to let the engine run continuously.
- when the weather is cold, it is, however, recommended to let the engine run to keep the hydraulic oil warm
- It is recommended to also leave the combustion engine running between the operations, to ensure the battery remains well charged
- check the stability and condition of the base regularly during the operation, taking into account the weather and ground conditions
- the electric timer of the lift automatically disconnects the supply voltage (12 VDC) in about 1 hour after the electric motor or the combustion engine has been turned off.
- Re-activate the power supply by pressing the start button either in the chassis control centre or in the platform control centre.

When moving the platform, remember the following

- beware of high voltage power lines
- do not touch open electric wires
- do not throw objects from the platform
- do not damage the lift
- do not damage other devices

**DANGER****Do not take additional load in the upper position.**

Do not exceed the max. allowed lateral force (400N) load the platform vertically more than what is allowed

Työkorin laskeminen kuljetusasentoon:

Aja teleskooppi aina ensin täysin sisään ja kori kohtisuoraan puomiin nähden ennen puomin laskua kuljetustuelle.

NOTICE

Do not damage the tow-bar jockey wheel while lowering the platform to transport position

When leaving the lift

- drive the lift to a safe position, preferably to the transport position
- switch off the power unit
- prevent unauthorized use of the lift by locking the control centre cover

5.2.3. Special instructions for winter use

The lowest allowed operating temperature of the lift is -20 °C

In cold conditions do the following special actions in addition to normal start-up procedure.

1. if the temperature is below zero, let the power unit run for a few minutes before starting the movements
2. start with a few movements to warm-up oil in the cylinders and to ensure proper operation of the valves
3. check that the limit switches and the emergency descent devices are operational and clean (from dirt, snow, ice, etc.)
4. protect the control panel and the platform from snow and ice whenever they are not in use



Always keep the lift free from dirt, snow etc.

5.2.4. Measures to be taken at the end of the working day

At the end of a workday:

1. Retract the telescope boom completely.
2. Check that the platform is perpendicular to the boom.
3. Lower the boom/platform onto the support on the chassis.
The limit switch on the transport support prevents operation of the support outriggers if the platform is not down
4. Close the cover on the platform control panel.
5. Turn the key switch to OFF-position and turn off the main switch .
6. If you want to recharge the battery, leave the mains cable connected; otherwise disconnect the lift from the mains supply.
7. Make sure that the covers are locked.

NOTICE

With respect to the operation and durability of the batteries, it is beneficial to connect them for recharging at the end of each workday, irrespective of their remaining level of charge. Keeping the batteries in storage without charging them first shortens their service life and flat batteries also freeze easily.

5.3. TRANSPORT

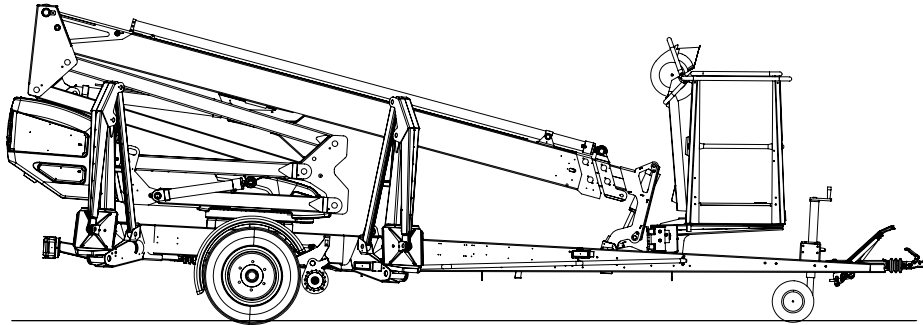
The lift can be moved by towing or with the platforms driving device.



Moving the lift is only allowed in the transport position. No persons or other additional load is allowed on the platform while transport.

5.3.1. Preparing the lift for transport

The lift must be in transport position.



Prepare the lift for transport as follows:

1. Retract the telescopic boom fully.
2. Check that the platform is perpendicular to the boom.
3. Lower the boom/platform onto the support on the tow-bar. The limit switch on the transport support prevents the operation of the support outriggers if the platform is not down
4. Close the cover of the platform control centre.
5. Turn the selector switch (1) to position "chassis control centre LCB".
6. Lift the support outriggers.
 - first the rear support outriggers 3-4 (do not damage the rear lights)
 - then the front support outriggers 1-2 (do not damage the jockey wheel)
7. Make sure that the covers are locked.

If you intend to tow the lift:

1. Apply the parking brake.
2. Make sure that the driving device is disconnected.
3. Turn the selector switch to position OFF and disconnect the lift from the power supply.

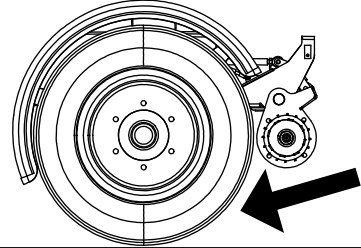
5.3.2. Driving with the driving device

The hydraulic driving device is intended for moving the lift within the work area if the towing vehicle cannot be used.



During transfer in rough terrain, try to stay above the machine.

4. Turn the selector switch (1) to position "chassis control centre LCB".
5. Start the electric motor
(With combustion engine, start the engine and set the engine revolutions at 3/4 of the maximum speed. The running speed of the power unit affects the speed of driving.
6. Make sure that the platform is in the transport position and the outriggers are lifted in the upper position
7. Make sure that the mains cable is long enough to cover the whole travel distance (power supply from mains).
8. Switch the driving device to the drive position
9. Release the parking brake
10. Drive the lift with the drive controls

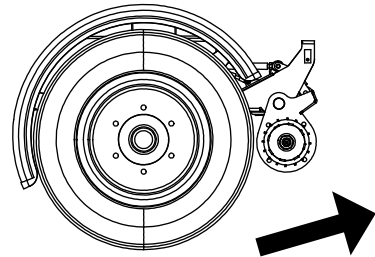


CAUTION

Do not drive the jockey wheel into obstacles or potholes. If one of the wheels bumps into an obstacle, the lift may turn abruptly.

After driving:

1. apply the parking brake
2. Switch off the driving device.
3. Disconnect the driving device from the wheel



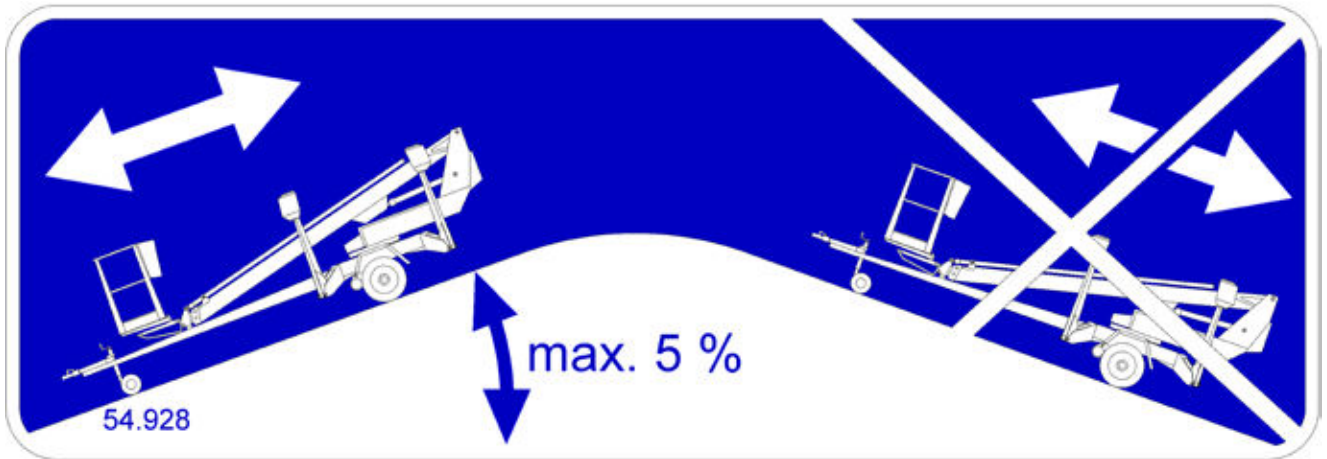
NOTICE

Do not extend the jockey wheel tube too much. It increases the risk of damage.

When moving the lift using the driving device, a suitable length for the jockey wheel's stem can be achieved by adjusting the gap between the lower surface of the tow-bar/brake rod and the wheel to 1-3 cm. Then the wheel may turn freely.

When driving on a slope:

1. When driving on a slope, the tow-bar must always point towards the descent. Never drive with the driving device with the tow-bar pointing towards the ascent.
2. Place chocks under the wheels before disconnecting the device from the towing vehicle.
3. Always apply the handbrake before disconnecting the lift from the towing vehicle.
4. Only use the handbrake as a parking brake or for emergency stopping.
5. When transferring the lift using the driving device:
 - take care not to allow the wheel to roll over your foot
 - look out for sudden sideways movements of the tow-bar
 - be careful not to cause danger to other people and the environment
6. Do not move the device on a slope using only hand-power. You may lose control over it and cause an injury.
7. Never park a vehicle combination on a slope.
8. Never leave the lift on a slope being supported only by the self-braking action of the driving device.



Do not drive downhill with the driving device, if the inclination of the surface is more than 5 per cent, i.e., more than 1/20 (corresponding to a descent of 0.5 m over a distance of 10 m). If the gradient of the surface is greater than this, you may lose control of the device.

5.3.3. Towing the lift

Connecting to the towing vehicle

1. Lift up and push forward (in the driving direction) the handle of the ball-coupling. Now the ball-coupling is released.
2. Press the ball-coupling onto the towball using only a little force. The connection and locking take place automatically.



Always make sure, after the connection, that the ball-coupling is properly locked

1. Connect the emergency stop wires and light plug to the vehicle. Check the cable for chafing and proper operation of the wires.
2. Check the operation of the lights.
3. Carefully release the parking brake and make sure that its locking is in order and that its handle stays in the lower position.
4. Lift up the jockey wheel to the transport position.



Clean and lubricate the ball-coupling regularly.

In particular, if you are parking or disconnecting the lift from the towing vehicle on a slope, apply the parking brake as firmly as possible. After having applied the parking brake, push the lift backward to make the reverse automatics release the brake shoes. The spring cylinder pulls the parking brake tighter, and the brakes of the vehicle will again be properly engaged.

Adjust the brakes according to the service instructions.
Place chocks under the wheels as an additional precaution.

NOTICE

While towing, in addition to the instructions in this manual, the user must also observe the road traffic legislation, regulations valid at the work site and towing instructions of the towing vehicle.

Always ensure before towing:

- transport position of the outriggers
- locking of the ball-coupling
- operation of the lights, connection of the cable
- that the parking brake is disengaged
- condition and pressure of the tyres
 - rear axle 450 kPa (4.5 bar)
 - jockey wheel 250 kPa (2.5 bar)
- attachment of the safety wire
- locking of the brakes after the transportation
- locking of the jockey wheel in its upper position
- **that the driving device is disconnected from the wheel**
- that there is no additional load on the platform



Place chocks under the wheels while disengaging the lift from the towing vehicle.

5.4. LIFTING THE DEVICE

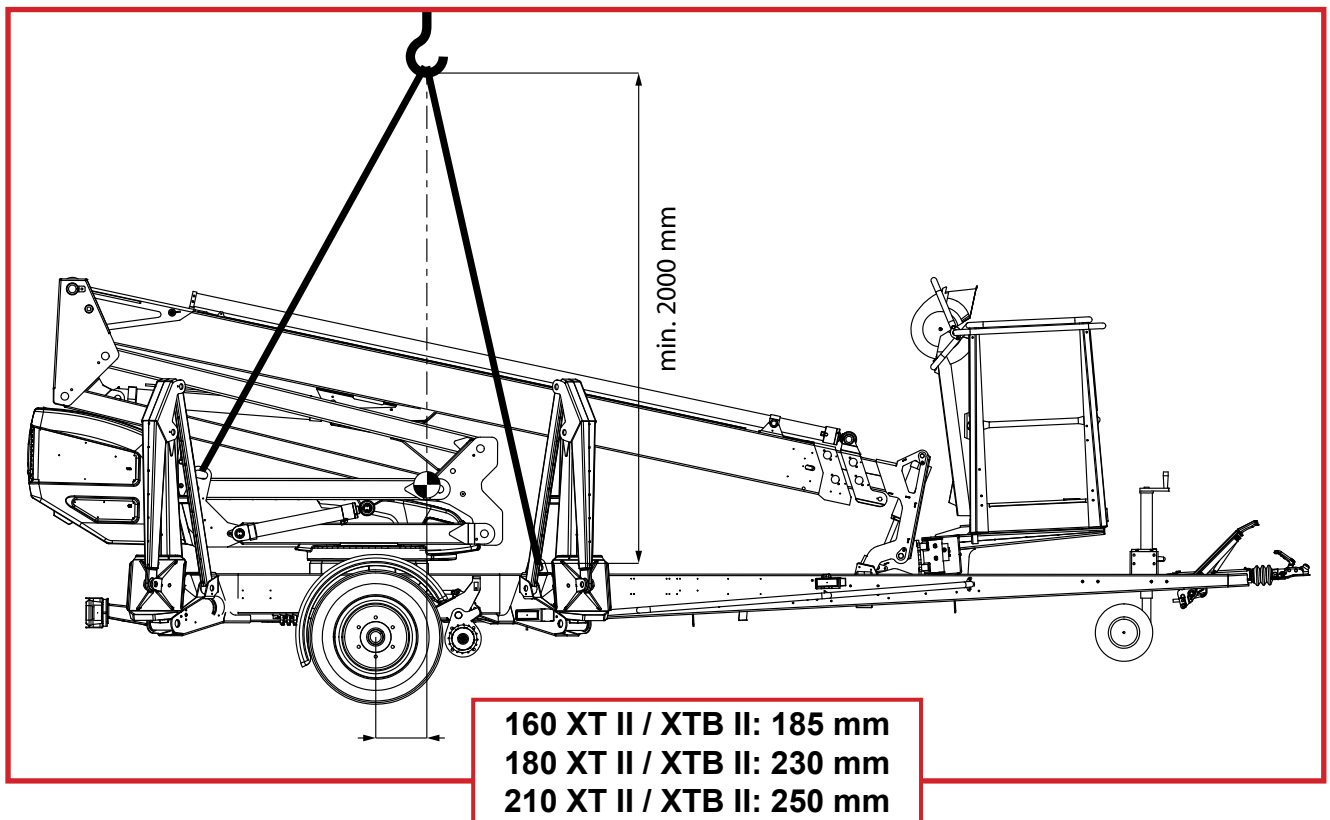
The device can be lifted from the lugs shown in the picture. Lugs are placed symmetrically on both sides. Lifting lugs are also marked in the machine with instructional labels.

During lifting the platform must be in transport position. Remove all loose material and other excess load from the platform before lifting.

Use a suitable crane and lifting accessories. Make sure that the crane and other lifting equipment are strong enough for the weight of the device. Check the weight from the technical specifications.



Be careful not to damage the device during the lifting!



5.5. LONG-TERM STORAGE

Clean the machine carefully, lubricate it and apply protective grease to it before putting it into storage for a longer period of time. Repeat the cleaning and lubrication procedures while resuming the operation.

NOTICE

If you leave the lift standing for a longer period of time, for example over the winter, we recommend propping it up to release any load from the wheels.

The periodic inspections must be executed following the steps described in the instructions.

5.6. IN CASE OF EMERGENCY

5.6.1. When at risk of losing stability

Reduced stability can be caused by a fault in the lift, the wind or other lateral force, collapse of the standing base or negligence in providing sufficient support. In most cases one sign of reduced stability is the inclination of the lift.

1. If there is time, try to find out the reason for the reduced stability and the direction of its effect. Warn other people on the work site using the alarm signal.
2. If possible, reduce the load from the platform in a safe manner.
3. Reduce the outreach to the side by retracting the telescopic boom using the emergency descent system. Avoid abrupt movements.
4. Turn the boom away from the danger zone, i.e. to a position where the stability of the lift is normal.
5. Lower the boom.

If the stability has been lost as a result of a fault in the lift, repair such a fault immediately.



Do not use the lift until the fault has been repaired and the condition of the lift has been verified.

5.6.2. In case of overloading

1. If there is time, try to find out the reason for the reduced stability and the direction of its effect. Warn other people on the work site using the alarm signal.
2. If possible, reduce the load from the platform in a safe manner.
3. Reduce the outreach to the side by retracting the telescopic boom using the emergency descent system.
4. The green light becomes illuminated when the overload situation is reset. After this the machine may be operated normally.

5.6.3. In case the power supply is interrupted

(power unit / combustion engine)

As a precaution against possible power failure, the lift is equipped with a battery operated emergency descent system.

Lower the boom using the emergency descent system

1. Start the emergency descent system from the pushbutton 20 on the platform or 5 on the chassis. The emergency descent works only while the button is pressed down.
2. Use the telescope in -button (6 or 21) if the set value of the RK5 has been exceeded.
3. Using the emergency descent, retract first the telescope completely, then lower the boom, and finally, turn the boom
4. Establish the reason why the energy supply was interrupted.

The emergency descent system can also be used for raising the support outriggers to the transport position:

Setup of the system

- battery 12V 44Ah
- recharger
- hydraulic unit 12 VDC

The hydraulic unit comprises:

- pressure relief valve, set value 16 MPa (160 bar)
- check valve
- direct current motor 800W

Servicing the battery

the system incorporates an automatic battery recharger with short circuit and overheat protection

- output 125 W
- charging voltage 13.7–14.7 V
- rated current 10 A

Always check the condition of the emergency descent system battery before putting the lift into operation.

5.6.4. In case the emergency descent system is not operational

In case of a malfunction where even the emergency descent system does not operate, try to warn other personnel present on the site so that they can help or call for more help. When help arrives:

- try to restore the power supply required for normal operation
- make the emergency descent system operational by, for example, changing the battery so that the person on the platform can be lowered safely.
- resume normal operation by other means

Always check the condition of the emergency descent system battery before putting the lift into operation.

6. FAULT FINDING

FAULT	REMEDY
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1. Electric motor cannot be started by depressing the start button, although the selector switch 1 is in position LCB or UCB

The emergency stop button has jammed in the lower position.	
Fuse F1 has blown.	Replace the fuse (10A).
No mains supply (230 VAC) to the selector switch.	Check the extension cords, possible distribution boards and fuses.
Fault current safety switch has tripped.	Reset the fault current safety switch.
No direct-current supply (12VDC).	Main switch has been turned off, turn on the switch.

2. No power supply to the lift, although the main switch is on and the selector switch is in position LCB or UCB

Power supply has not been activated.	Press the start button to activate the power supply.
One of the fuses F1, F11 or F12 has blown.	Change the fuse and press the start button.
Battery is flat.	Recharge the battery.

3. Power unit does not start

Battery is flat.	Recharge the battery.
The mains cable is plugged.	Disconnect the plug from the mains.
No direct-current supply (12VDC).	Main switch has been turned off, turn on the switch.

4. Power unit cranks but does not start

Fuel tank is empty.	Fill the fuel tank.
Choke is off.	Press the choke button (cold engine).
Throttle lever in idling position.	Increase the engine revolutions.

5. None of the platform movements is operational, although the electric motor is running and the selector switch is in position 2 or 3

Boom has been overloaded.	Retract the telescope via buttons 6 or 21 until the platform returns inside its operating range (the green light in the platform control centre is illuminated).
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FAULT	REMEDY
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6. Outriggers do not move

Boom is not resting on the transport support.	Drive the boom onto the transport support.
The selector switch is in the wrong position.	Turn the selector switch to position LCB.
Limit switch on the boom support has not closed.	Drive the boom onto the transport support and check the operation of the limit switch RK3.

7. Malfunctions of platform movements – only one of the movements can be operated

Lifting and lowering of the boom and the extension of the telescope are not operational, the red light is illuminated on the platform and in the chassis control centre, and the buzzer is audible.	The boom has been overloaded; retract the telescope and retry the operation (automatic reset).
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10. None of the outriggers moves although the selector switch is in position LCB

The boom does not rest properly on the support.	Check the boom support and the operation of the RK3.
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18. Driving device does not operate, although the selector switch is in position LCB

Boom is not resting on the transport support.	Drive the boom onto the support.
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24. Wheel brakes overheat

Parking brake not completely released.	Release the parking brake completely.
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25. Ball-coupling is not locked

Inner parts of the ball-coupling dirty.	Clean and lubricate.
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With all other problems, please take the platform to a qualified DINO-service.

To avoid problems:

- Follow all operating, maintenance and safety instructions
- Be careful in situations with a risk of damage to the lift
- Keep the lift clean and protect it against moisture

NOTES

7. SERVICING AND MAINTENANCE

Maint.	Schedule	Person responsible	Reference
A	Daily	Operator	Operating instructions
B	1 month / 100 hours*	Competent person who is familiar with the lift	Maintenance instructions
C	6 months / 500 hours*	Competent person who is familiar with the lift	Maintenance instructions
D	Annually / 1000 hours*	Skilled technician who is well familiar with the structure and operation of the lift	Maintenance instructions
E	As needed	Skilled technician who is well familiar with the structure and operation of the lift	Maintenance instructions

* Service must be performed every indicated month or operating hour interval, whichever comes first.

NOTICE

In addition to daily maintenance, every user must do a worksite inspection before operating the lift.

C = Check (general checking of condition).

I = Thorough Inspection. Performed according to separate procedure described in maintenance instructions.

G = Grease

D = Do the replacements, repairs or other maintenance tasks described in the instructions

	Maintenance item	A	B	C	D	E
1	Condition of chassis structures, boom and work platform	C	C	C	I	
2	Bearings of the overload protection device joint		G	C/G	C/G	
3	Bearings of outriggers and outrigger cylinders		G	C/G	I/G	
4	Bearings of outrigger footplates and moving parts of outrigger limit switch system		G	C/G	I/G	
5	Bearings of boom and articulated arms		G	C/G	C/G	
6	Bearings of the platform		G	C/G	C/G	
7	Bearings of the levelling cylinders		G	C/G	C/G	
8	Bearings of the lifting cylinder		G	C/G	C/G	
9	Sliding surfaces / rolls of the telescope		C/G	C/G	C/G	
10	Bearings of the telescope cylinder			C/G	C/G	
11	Condition of cylinders				I	
12	Flyer-chain			G	I/G	
13	Slide pads and sliding pad clearances		C	C	C	
14	Turning device			G	I/G	
15	Electro-hydraulic rotating adaptor				C	
16	Tyres and tyre pressures	C	C	I	I	
17	Coupling / overrun device		C	G	I/G	
18	Jockey wheel slide and threads				I/G	
19	Brakes			C	C	

	Maintenance item	A	B	C	D	E
20	Axles and suspension				I	
21	Driving device		C	G	I	
22	Lights	C	C	C	I	
23	Hydraulic oil	C	C	C	D	
24	Hydraulic hoses, pipes and fittings	C	C	C	I	
25	Condition and attachment of battery, electrical devices and wiring		C	C	I	
26	Hydraulic pressure				I	
27	Condition of safety limit switches				C	
28	Operation of safety limit switches	C	C	C	I	
29	Operation of overload protection device			C	I	D
30	Load holding and load regulation valves			C	C	
31	Platform levelling system		C	C	C	
32	Platform control devices	C			I	
33	Emergency descend, emergency stop and sound signal	C	C	C	C	
34	Signs, labels and machine plates	C	C	C	C	
35	Instruction manuals	C	C	C	C	
36	Test loading				I	
37	Corrosion protection				C	D
38	Movement speed adjustment					D
39	Special inspection					D

Always lubricate the lift and apply a protective grease film immediately after the washing.

Special inspection is required if the lift has been damaged in a manner which may affect its load-bearing capacity or safe operation. For further instructions, see the maintenance instructions manual.

NOTICE

If the platform has a combustion engine power pack, check the engine manual for information on maintenance procedures required by the engine.

NOTICE

If the lift is operated under demanding conditions (in exceptionally humid or dusty environment, corrosive climate, etc.), the intervals between the oil changes and the other inspections shall be shortened to meet the prevailing conditions in order to maintain the operational safety and reliability of the lift.

7.1. INSPECTIONS REQUIRED BY AUTHORITIES

Inspections must be performed in accordance with local, state or federal regulations, legislation, directives, standards. The manufacturer recommends following inspections, as required by local authorities in platforms country of origin.

A pre-use inspection must be done before taking the platform to use for the first time and before first start-up after major repairs and alterations.

A thorough inspection and a test loading of the lift must be carried out at least once every twelve (12) months.

The platform should undergo a major inspection within ten (10) years after having been originally put into service. A major inspection includes non-destructive testing and inspection while dis-assembled.

A special inspection should be done if the platform has been exposed to exceptional circumstances which may have affected the structural integrity of critical components.

The inspections should be carried out on regular basis throughout the service life of the lift. If the lift is used under extreme conditions, intervals between the inspections shall be reduced.

The overall operating condition of the lift as well as the condition of the safety-related control devices shall be established in the regular inspections. Particular attention shall be paid to changes which affect the operational safety.

During inspections the notifications given in previous inspections, practical experience from use and information on performed repairs should be taken into account and can be implemented for better safety.

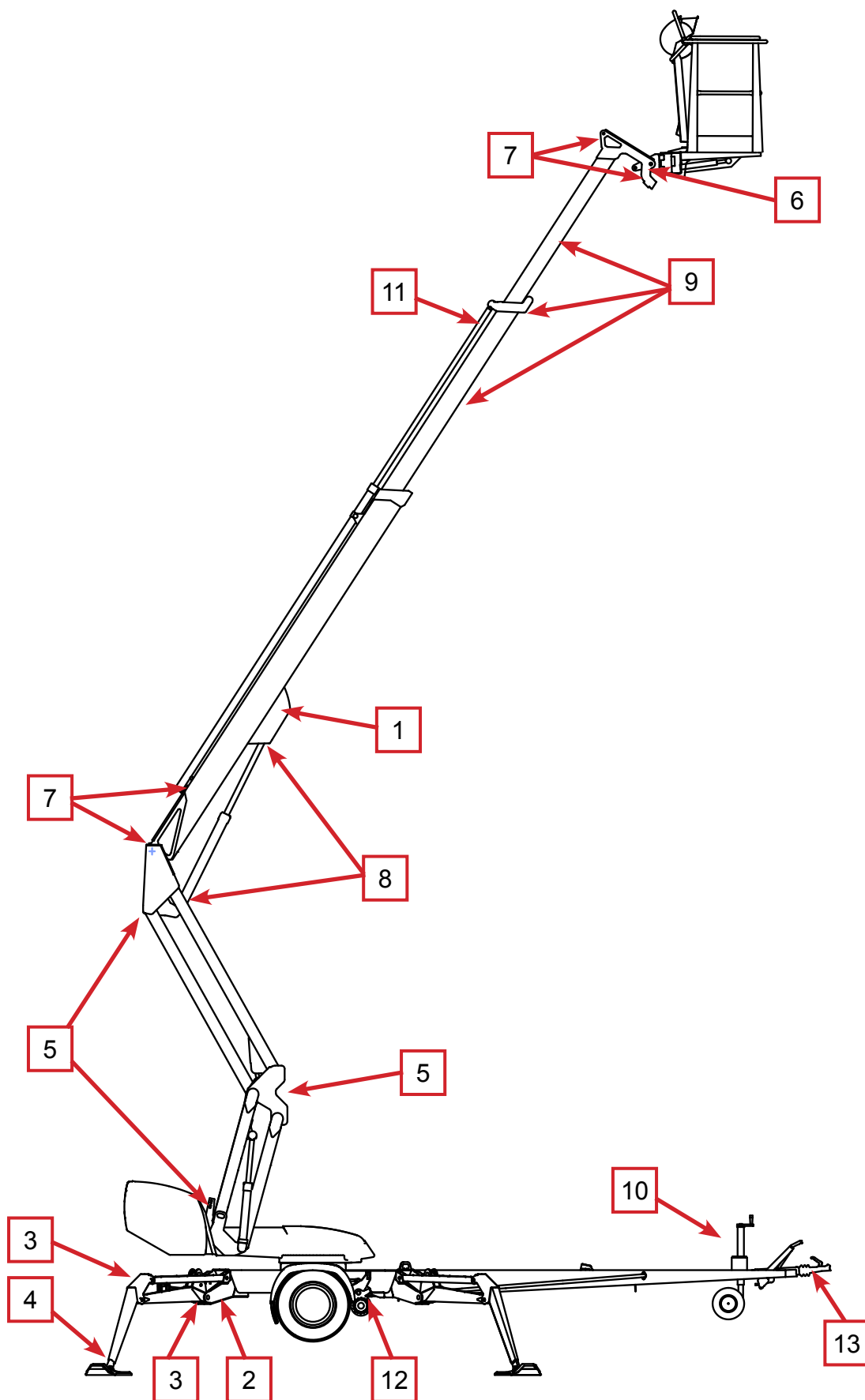
Major and special inspections shall be carried out by a competent person or competent body, who is familiar with the operation and structure of the lift. The competent person should periodically update their knowledge and be able to demonstrate their competency if so required.

A report should be made of the inspections and the reports should be kept with the unit stored in the space reserved for it.

NOTICE

Always check the local, state or federal regulations about aerial platform inspections and inspector qualifications from local authorities.

7.2. LUBRICATION PLAN



8. ROUTINE MAINTENANCE DURING OPERATION

This chapter describes the service and maintenance operations that the operator of the platform is responsible for.

Other maintenance operations require special training, tools and materials or specific measurements and adjustment values. They are separately described in maintenance instructions manual. Please contact your maintenance partner, dealer or manufacturer.

Make sure that all service and maintenance procedures are performed in time and according to instructions.



WARNING

Any faults which may affect the operational safety of the unit must be repaired before the lift is used for the next time

Keep the lift clean. Clean the lift carefully before any service and maintenance operations or inspections. Impurities may cause serious problems in for example in the hydraulic system.

Use original spare parts and service kits. See spare part list for detailed information on spare parts.

The first service after 20 hours of operation

- change the pressure filter element
- adjust the brakes according to the instructions (see point “Wheel brakes and bearings”)
- check the wheel bolts for tightness after about 100 km of driving

If the lift is operated under demanding conditions (in exceptionally humid or dusty environment, corrosive climate, etc.), the intervals between the oil changes and the other inspections shall be shortened to meet the prevailing conditions in order to maintain the operational safety and reliability of the lift.

The performance of the periodic servicing and the inspections is absolutely mandatory, because their negligence may impair the operational safety of the lift.

The guarantee will not remain valid, if the servicing and the periodic inspections are not performed.

8.1. DAILY MAINTENANCE TASKS

8.1.1. Condition of chassis, boom and work platform

Inspect visually the condition of access systems, work platform, platform gate and handrails. Check that the chassis and boom have no visible signs of structural damage.

8.1.2. Check the tyres and tyre pressure

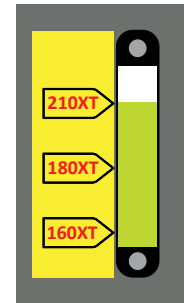
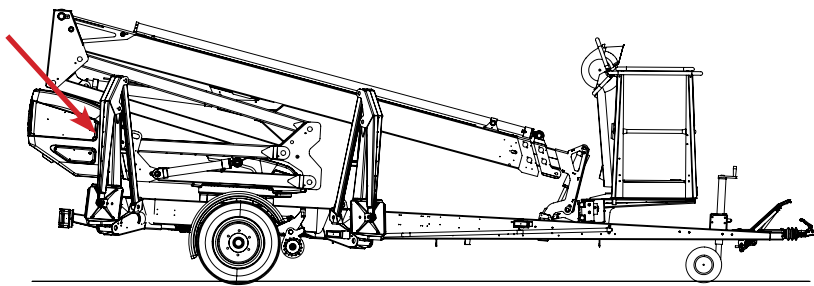
Inspect the condition of tyres visually and check that they are not flat.

8.1.3. Check the lights

Check all the warning and signal lights and trailer lights for road traffic.

8.1.4. Check the hydraulic oil

Check the hydraulic oil level while the platform is in transport position. Add oil if needed.



The oil tank is located under a cover on the right side of the device.

Check that the oil visible from the oil meter looks clean and normal (no excess foam etc.)

8.1.5. Check the hydraulic hoses, pipes and connectors

Inspect the condition of hydraulic hoses, pipes and connections visually. Make sure that there are no visible oil leaks.

Any externally damaged hoses or clashed pipes and connections must be changed.

8.1.6. Check the operation of safety limit switches

Test the correct operation of safety limit switches that prevent the boom and outrigger movements unless the platform is in a correct position.

1. Platform must be in transport position, outriggers up and the driving device connected.
2. Lift the boom from lower controls.

The boom must not work in any position of the control device.

3. Drive the outriggers down to operating position
4. Lift the boom so that the boom is not on the support
5. Drive the outriggers.

The outriggers must not work in any position of the control device.

8.1.7. Check the emergency descent, emergency stop and sound signal

Test the correct operation of emergency stop, emergency descent system and the sound signal from the lower controls and platform controls.

- lift the boom up approximately 1-2 meters and drive the telescope out 1-2 meters. While driving the movement, push down the emergency stop button. The movement should stop.
- Drive the telescope in and lower the boom by using emergency descent
- lift up the emergency stop button
- test the sound signal

8.1.8. Signs, labels and machine plates

Make sure, that all the plates, adhesive tapes and instructional labels on control stations are intact, clean and legible.

If the labels have started to come off or tear apart or if the symbols or texts are illegible the labels must be replaced.

Product numbers of labels are marked on the labels or they can be found in the spare part lists.

8.1.9. Instruction manuals

Check that the instruction manuals accompanying the platform are correctly stored on the platform and that they are legible.

9. TRANSFER OF OWNERSHIP

To product owner:

If you have purchased a used DINO lift covered by this manual from somewhere other than the manufacturer, please use this form to provide your information to the manufacturer via e-mail to the address:

info@dinolift.com

The updated ownership information allows you to receive information like safety bulletins or other campaigns concerning your lift.

Note: Leased or rented units do not need to be reported with this form.

Model: DINO _____

Serial number: _____

Previous owner: _____

Country: _____

Date of transfer: _____

Current owner: _____

Address: _____

Country: _____

Information of a contact person

Name and title: _____

Telephone: _____

E-mail: _____



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